

Data analysis

Benjamin Winkel

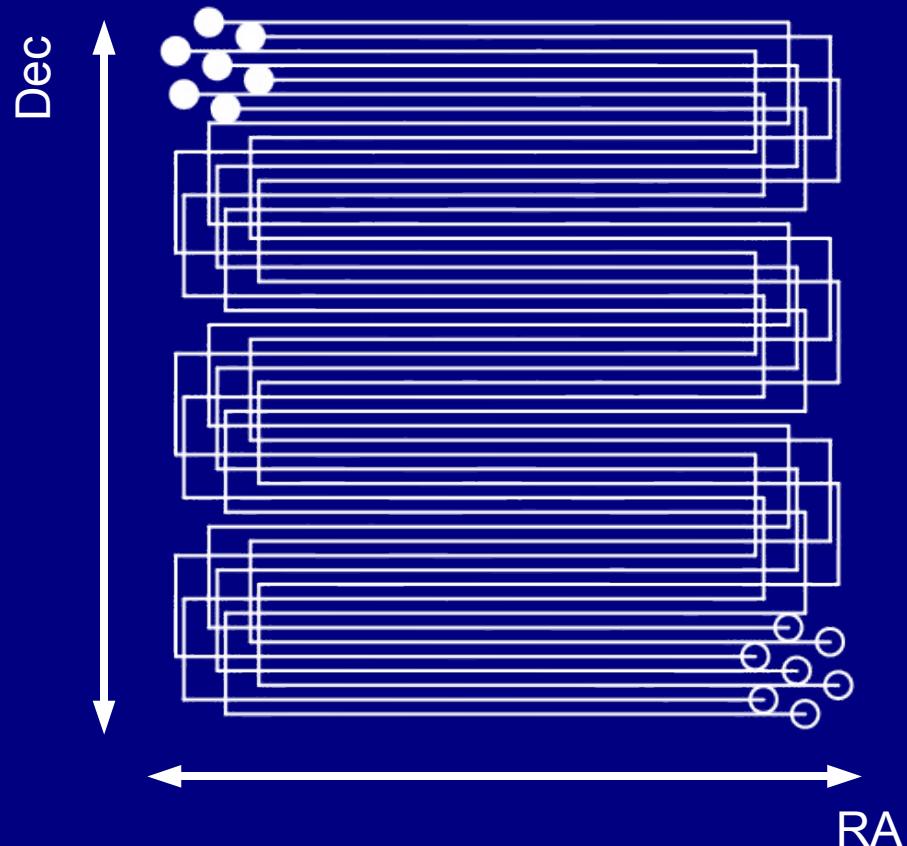
Map observations (spectroscopy)



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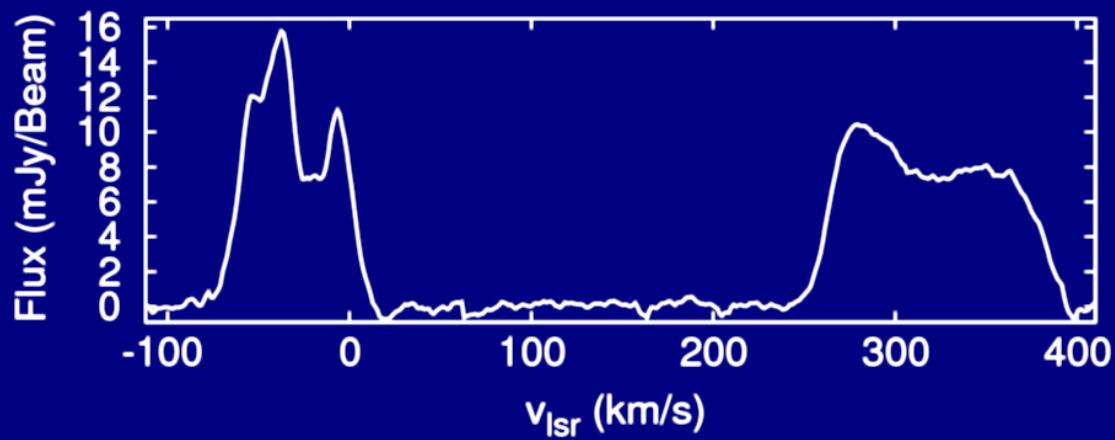
e.g., Zig-Zag scanning



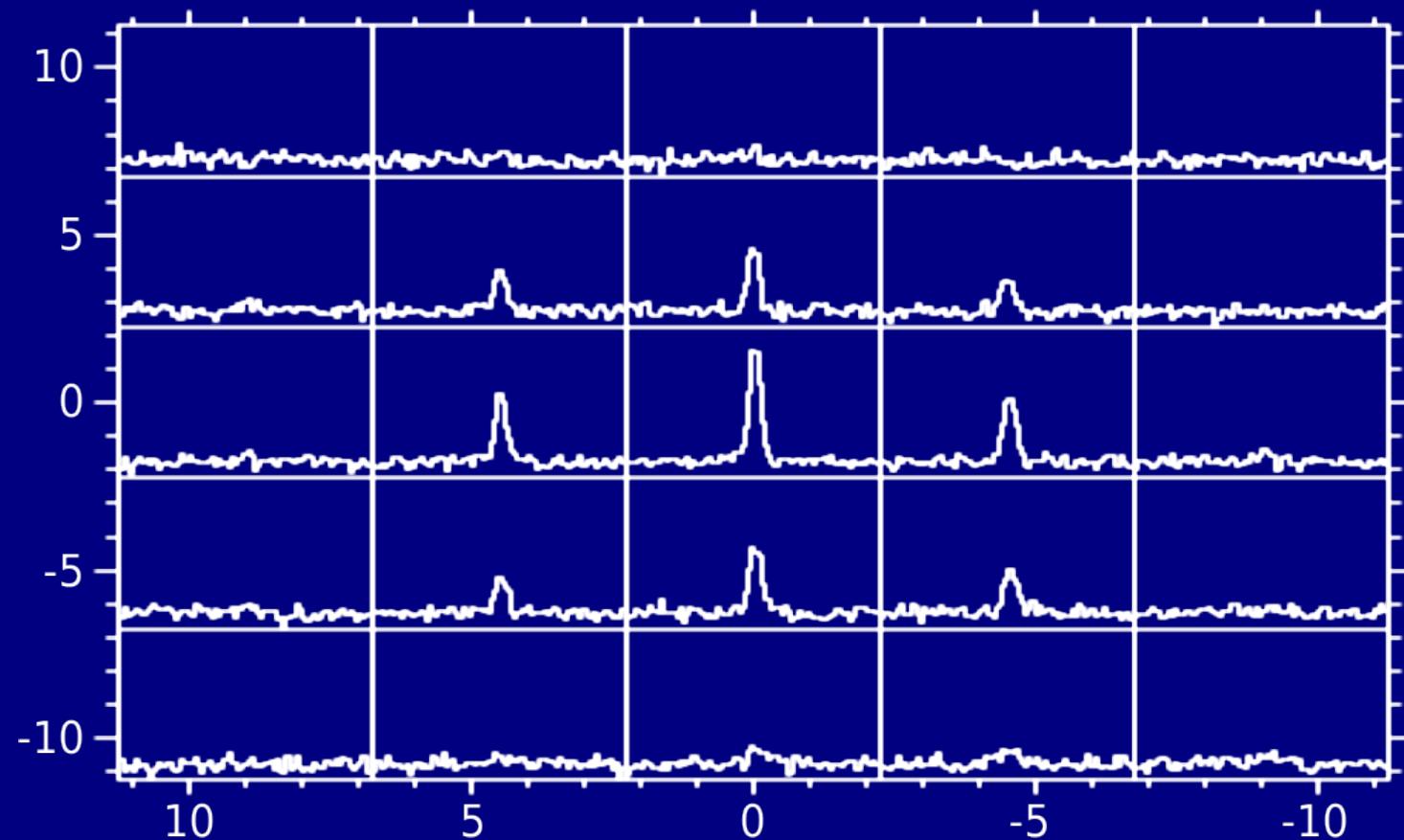
Map observations (spectroscopy)



N X

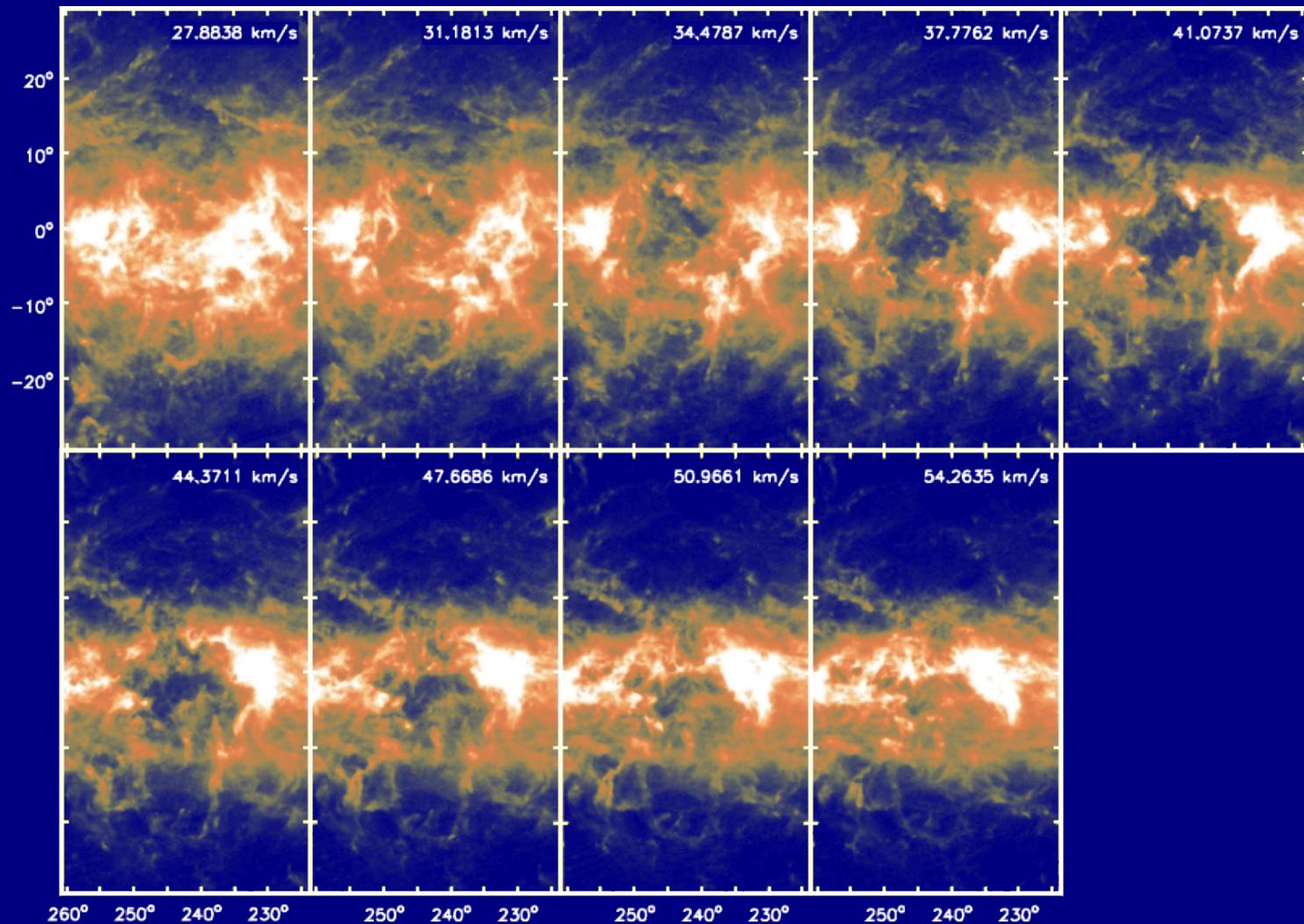


Map observations (spectroscopy)



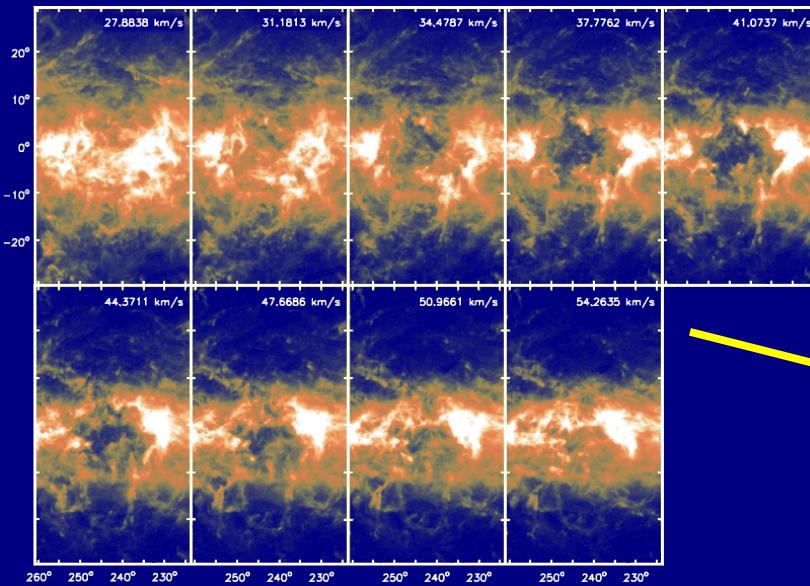
Brüns & Westmeier 2004

Map observations (spectroscopy)

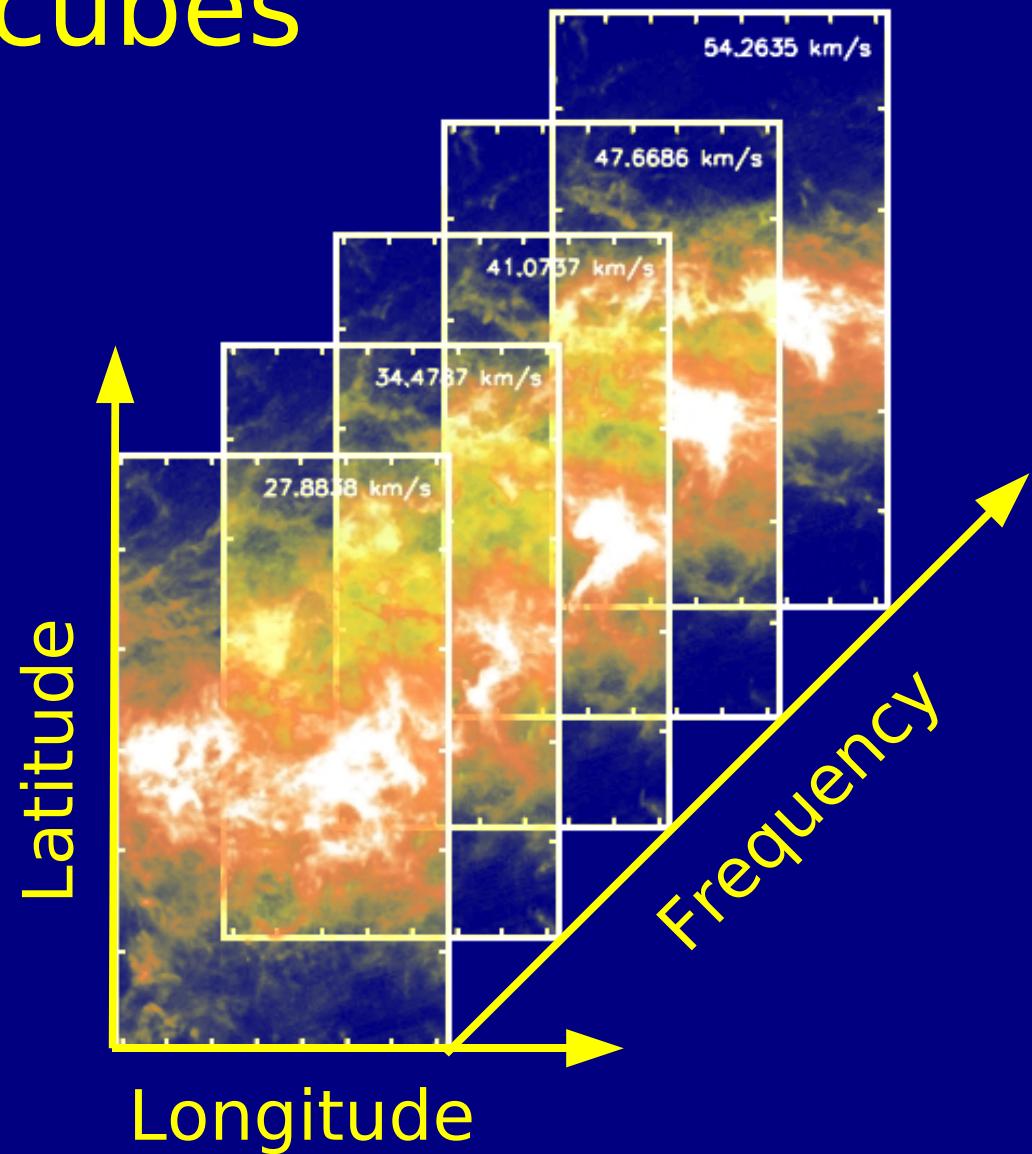


McClure-Griffiths et al. 2006

Data cubes



- 3D data structure
- But: objects in the data cube not 3D!

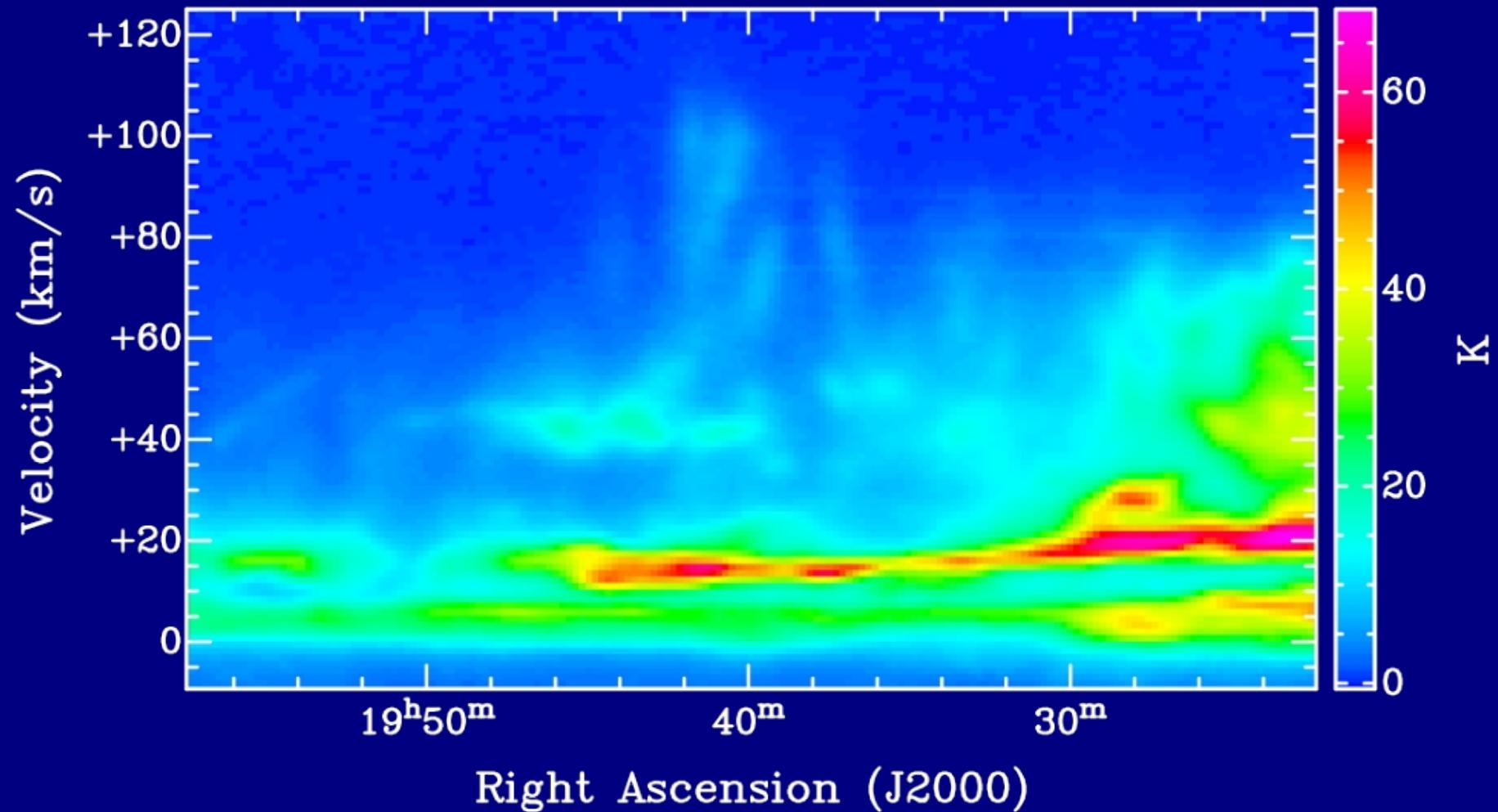


Data cubes

Movie...

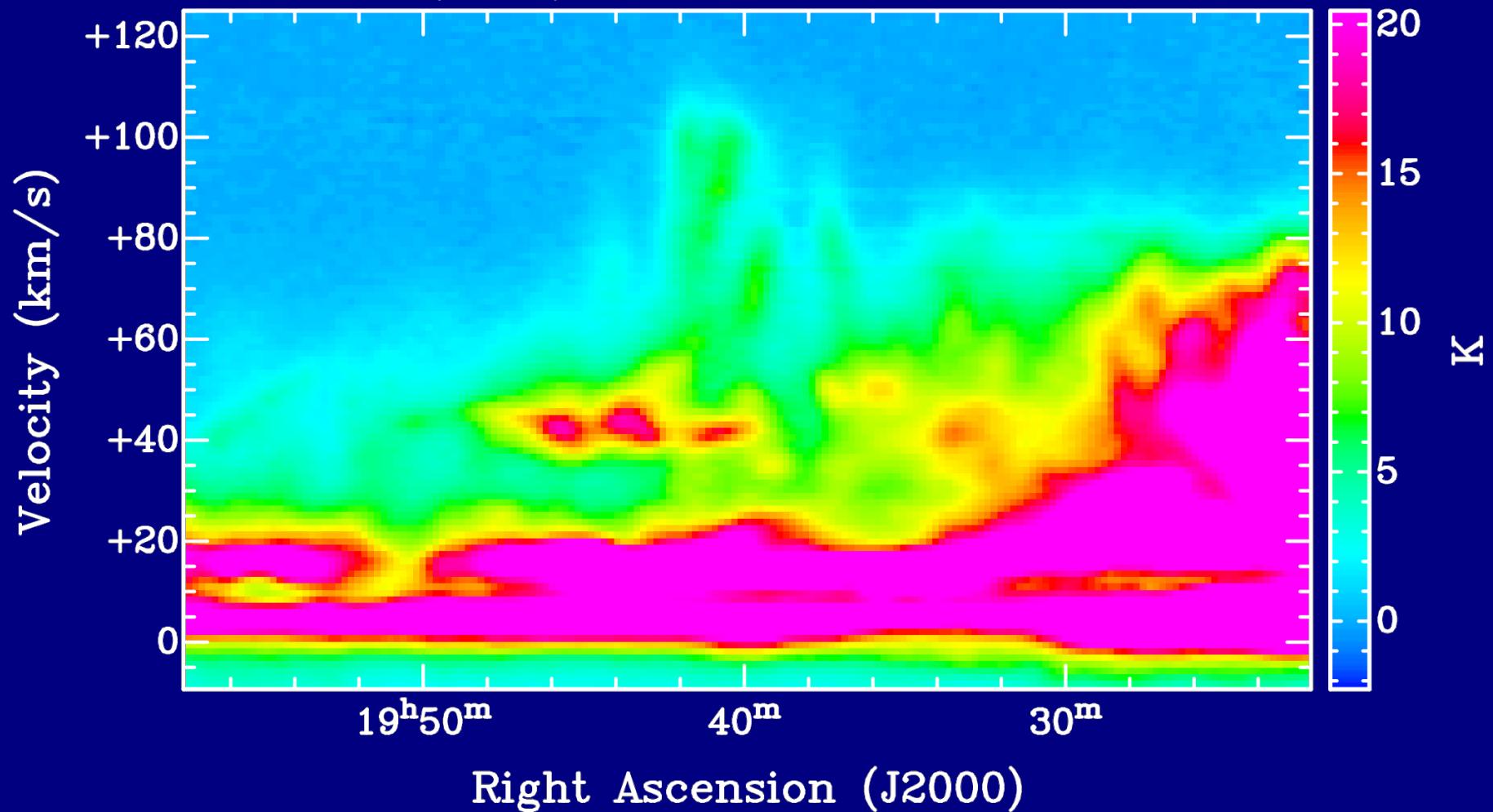
Data cubes: P-V diagrams

Dec: +08° 51' 36.32" (J2000)



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Data cubes: P-V diagrams

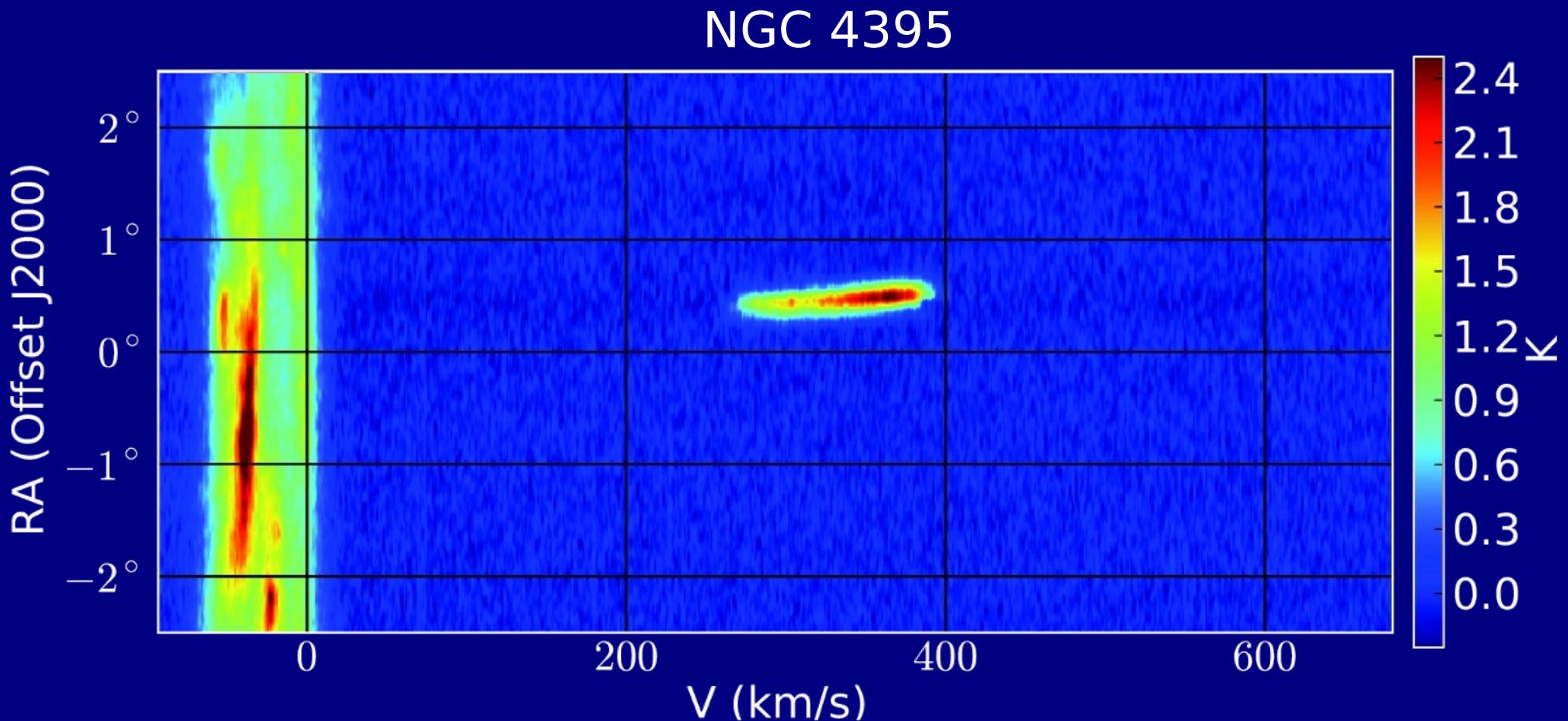


Image moments

Total intensity $\mathcal{M}_0 = \Delta v_i \sum_i p_i$ [K km/s]

Velocity field $\mathcal{M}_1 = \frac{1}{\mathcal{M}_0} \sum_i p_i v_i$ [km/s]

Dispersion $\mathcal{M}_2 = \sqrt{\frac{1}{\mathcal{M}_0} \sum_i p_i (v_i - \mathcal{M}_1)^2}$ [(km/s)²]

p_i . . . flux in spectral channel i

v_i . . . velocity of spectral channel i

Δv . . . width of a spectral channel

Image moments

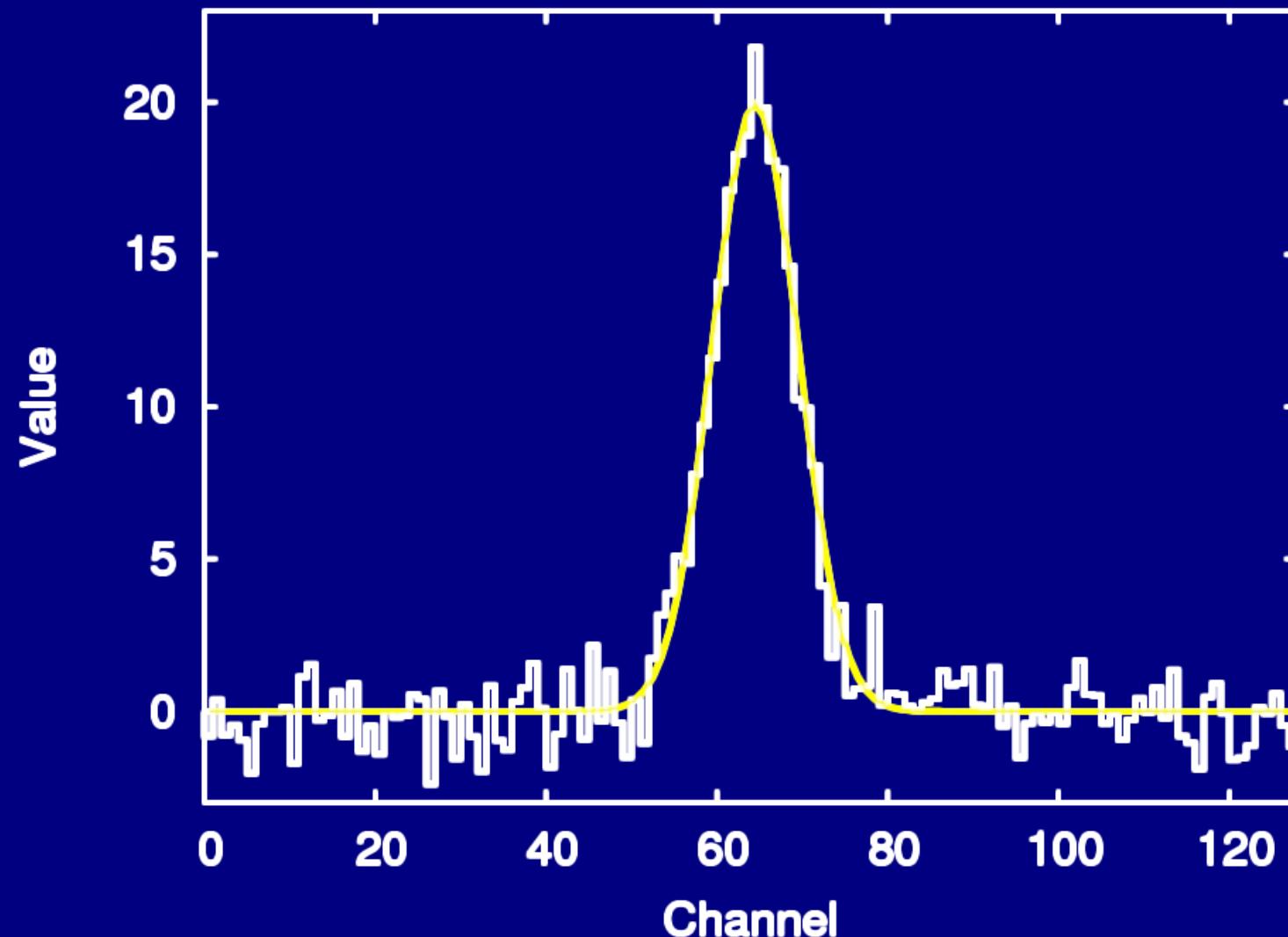


Image moments

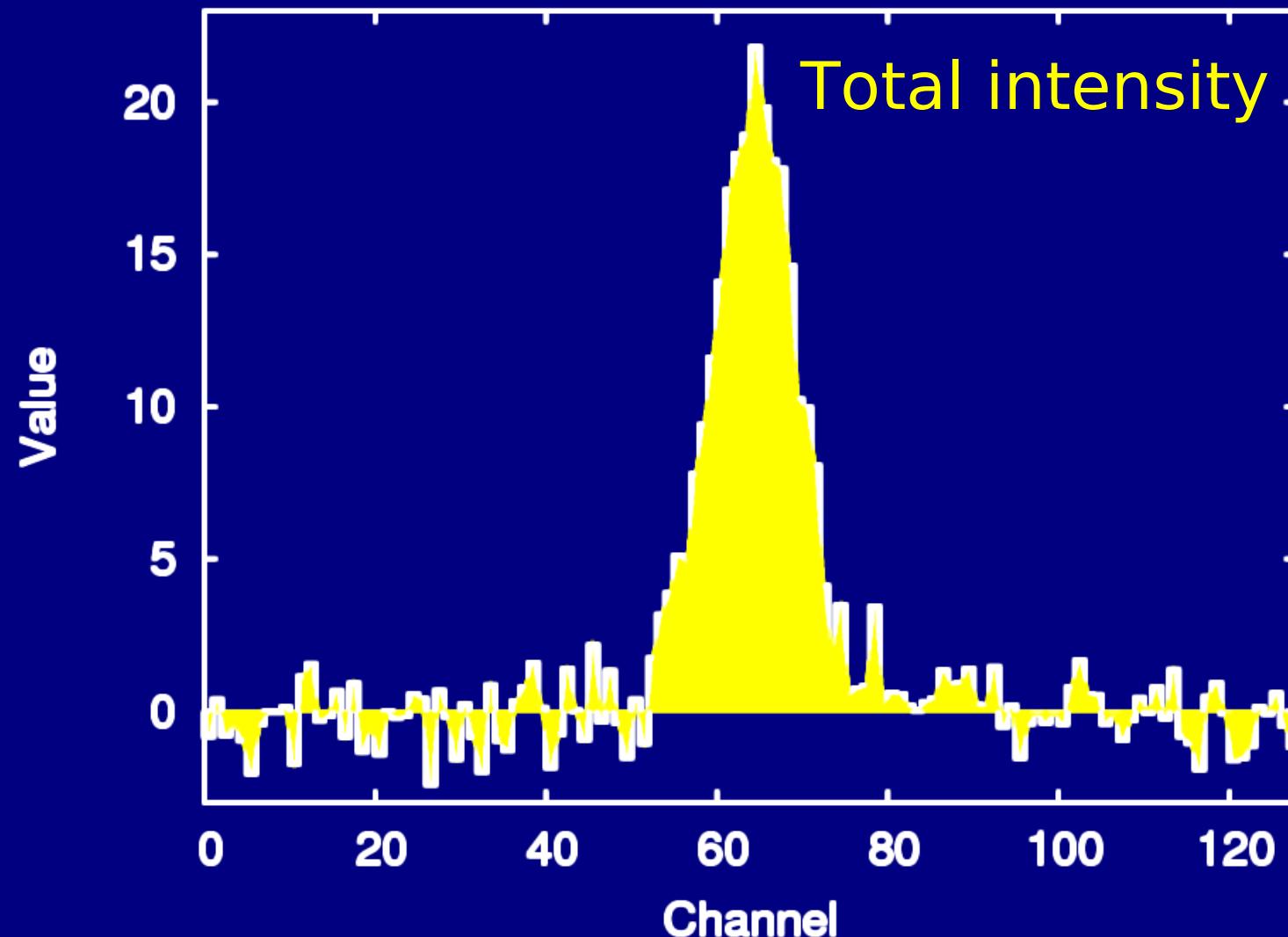


Image moments

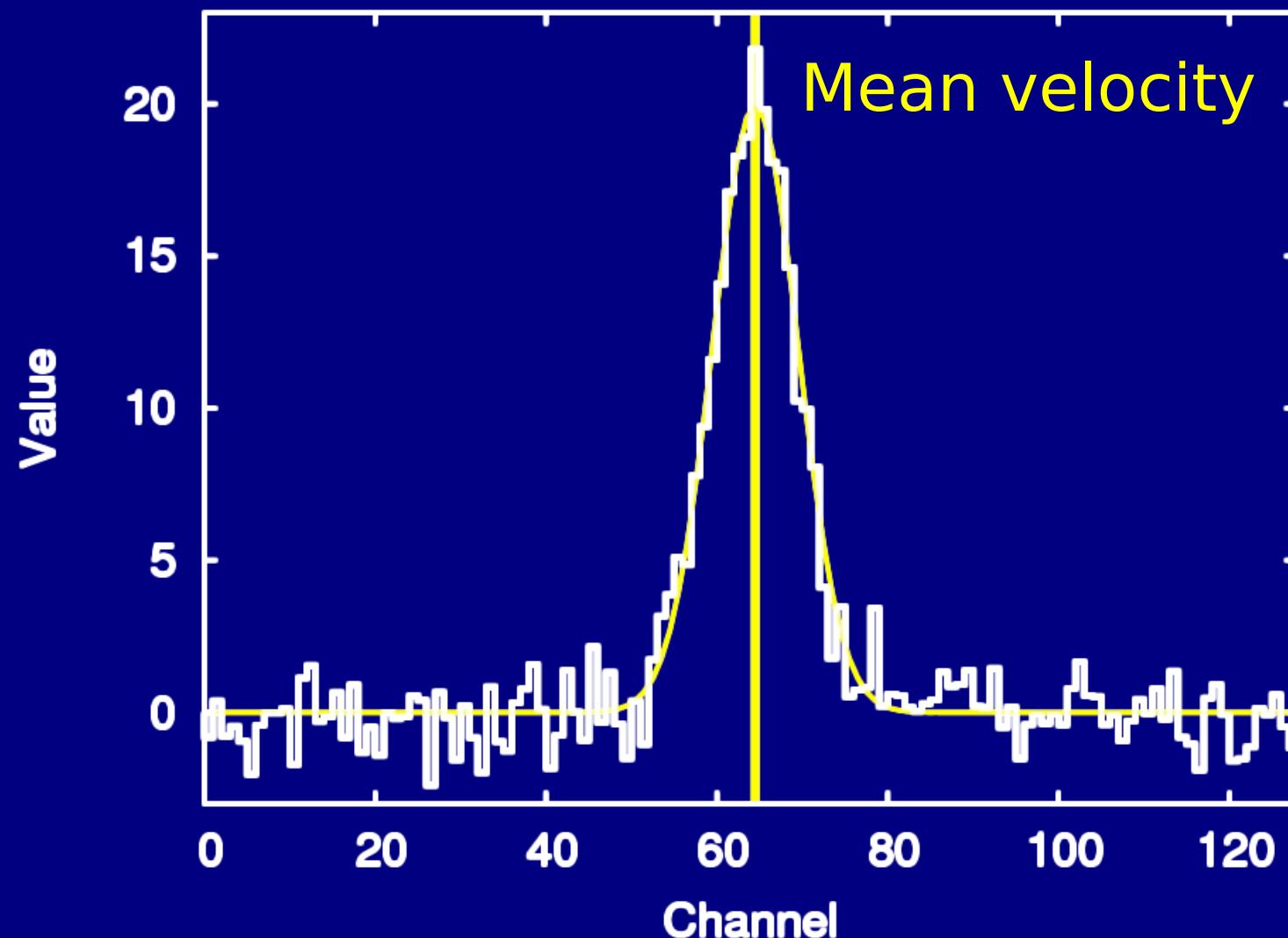
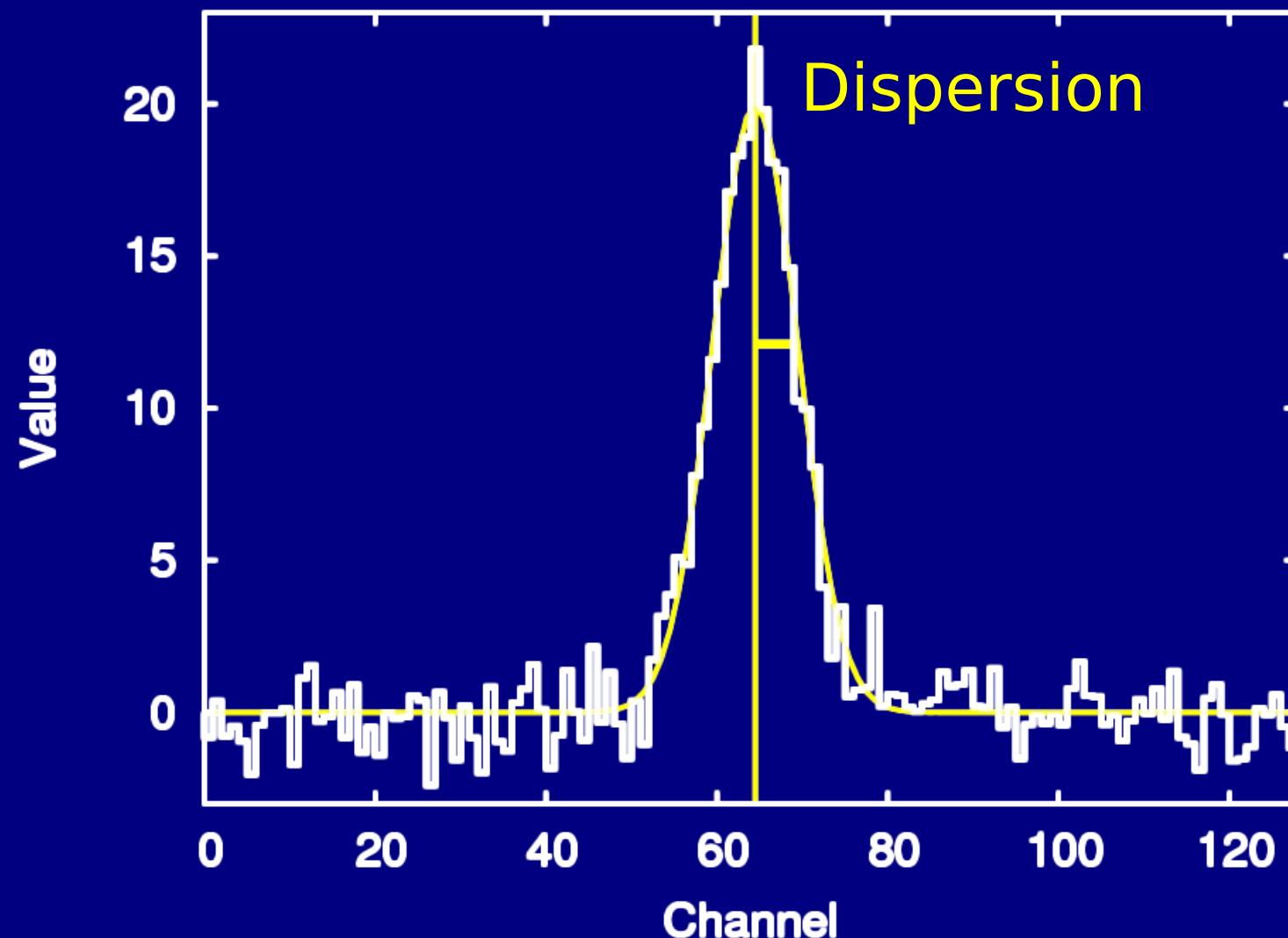
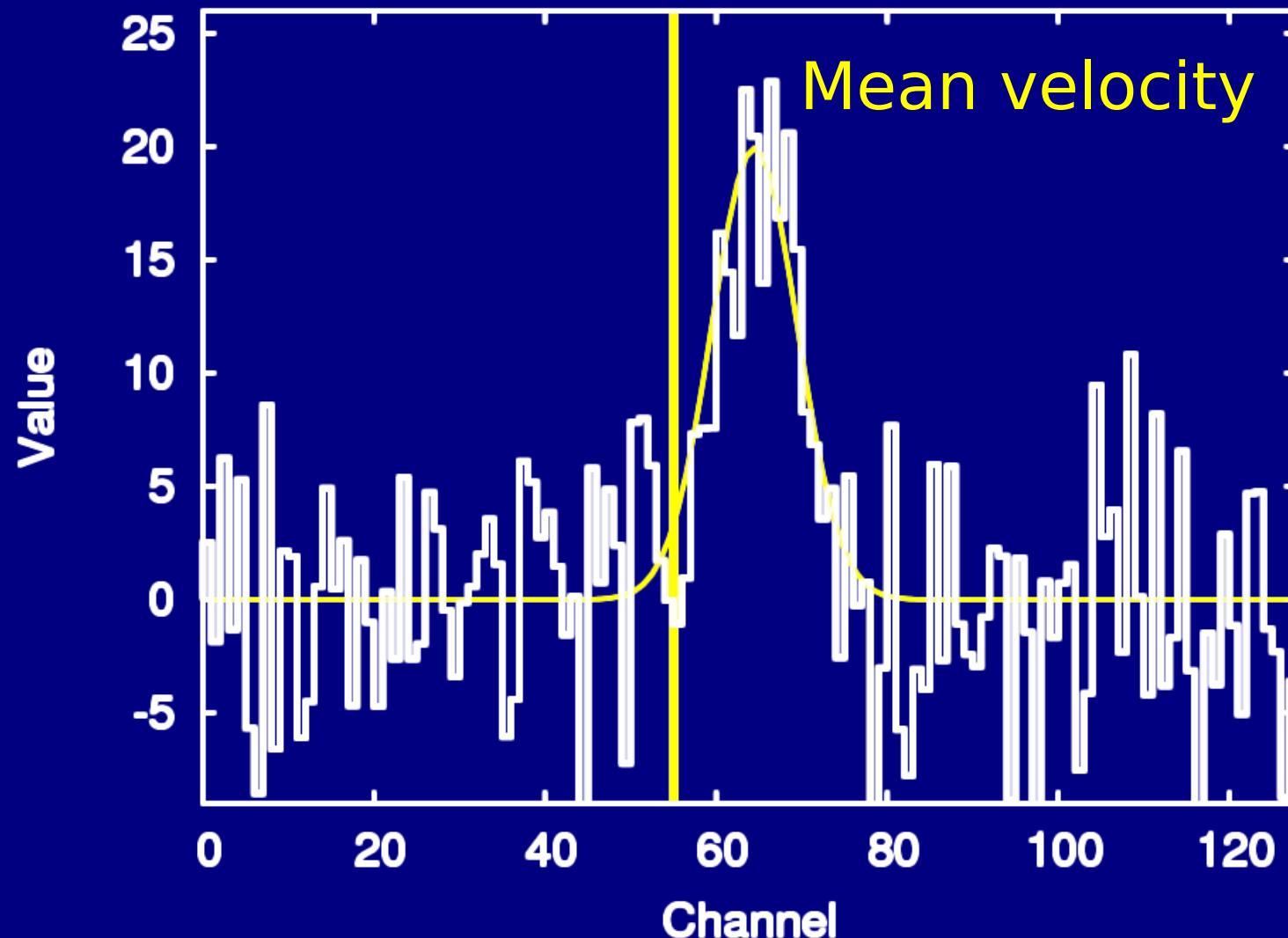


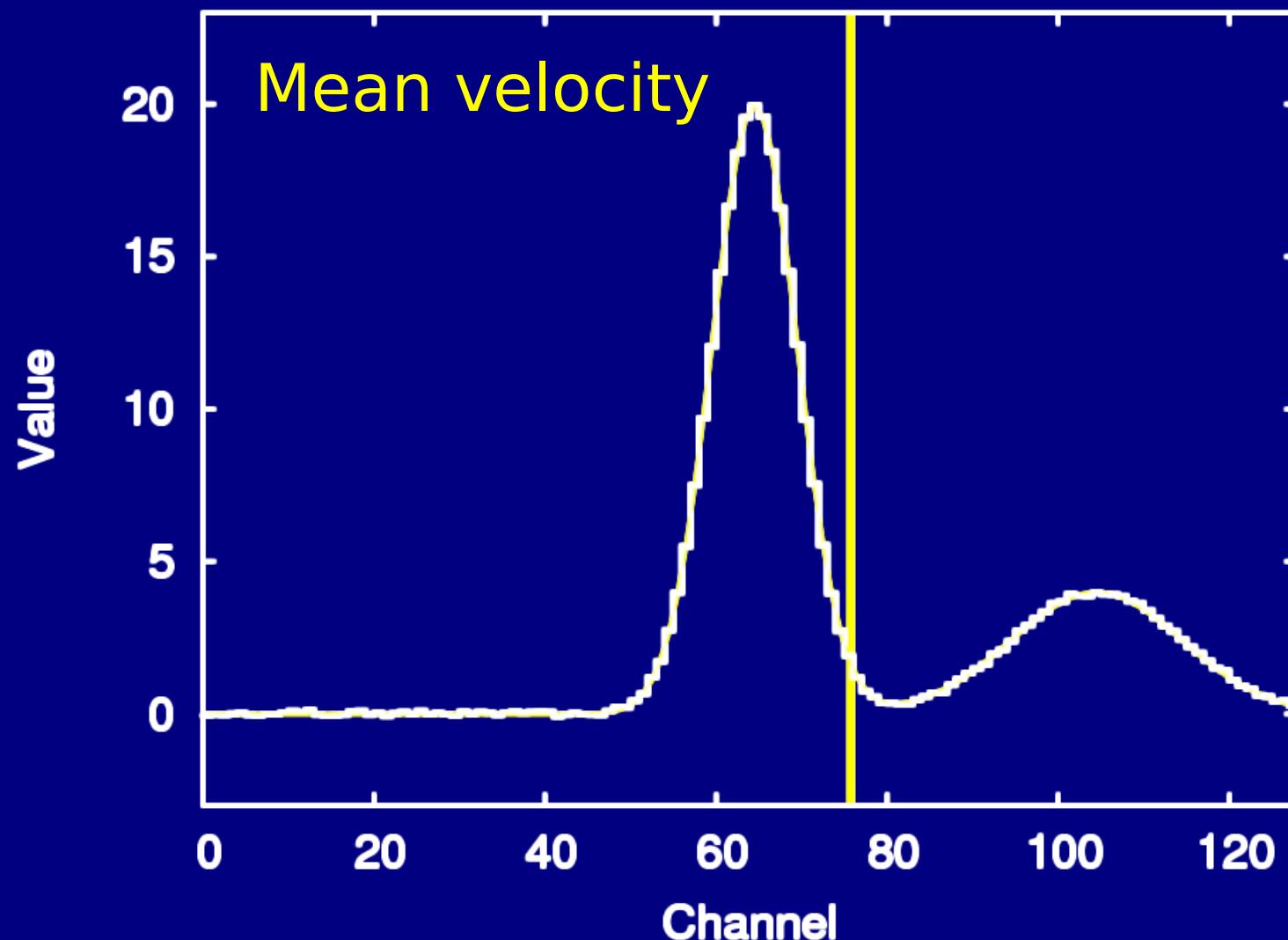
Image moments



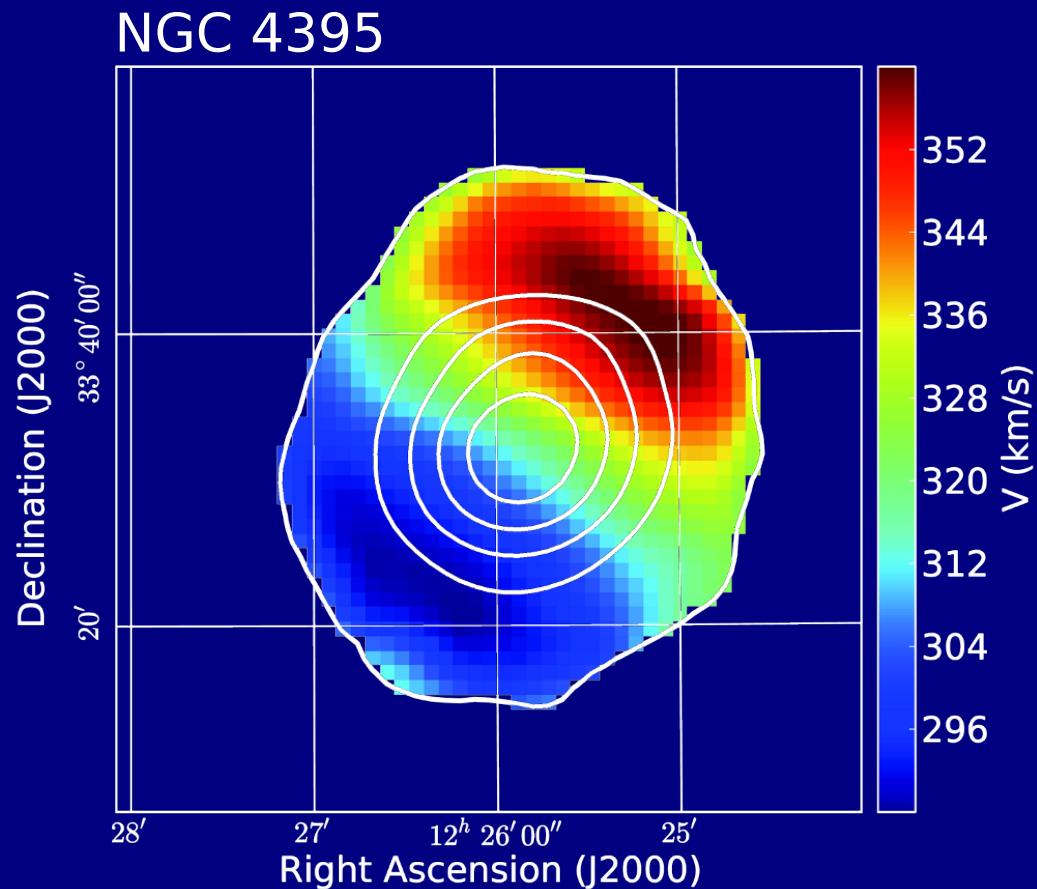
Moments: bottlenecks



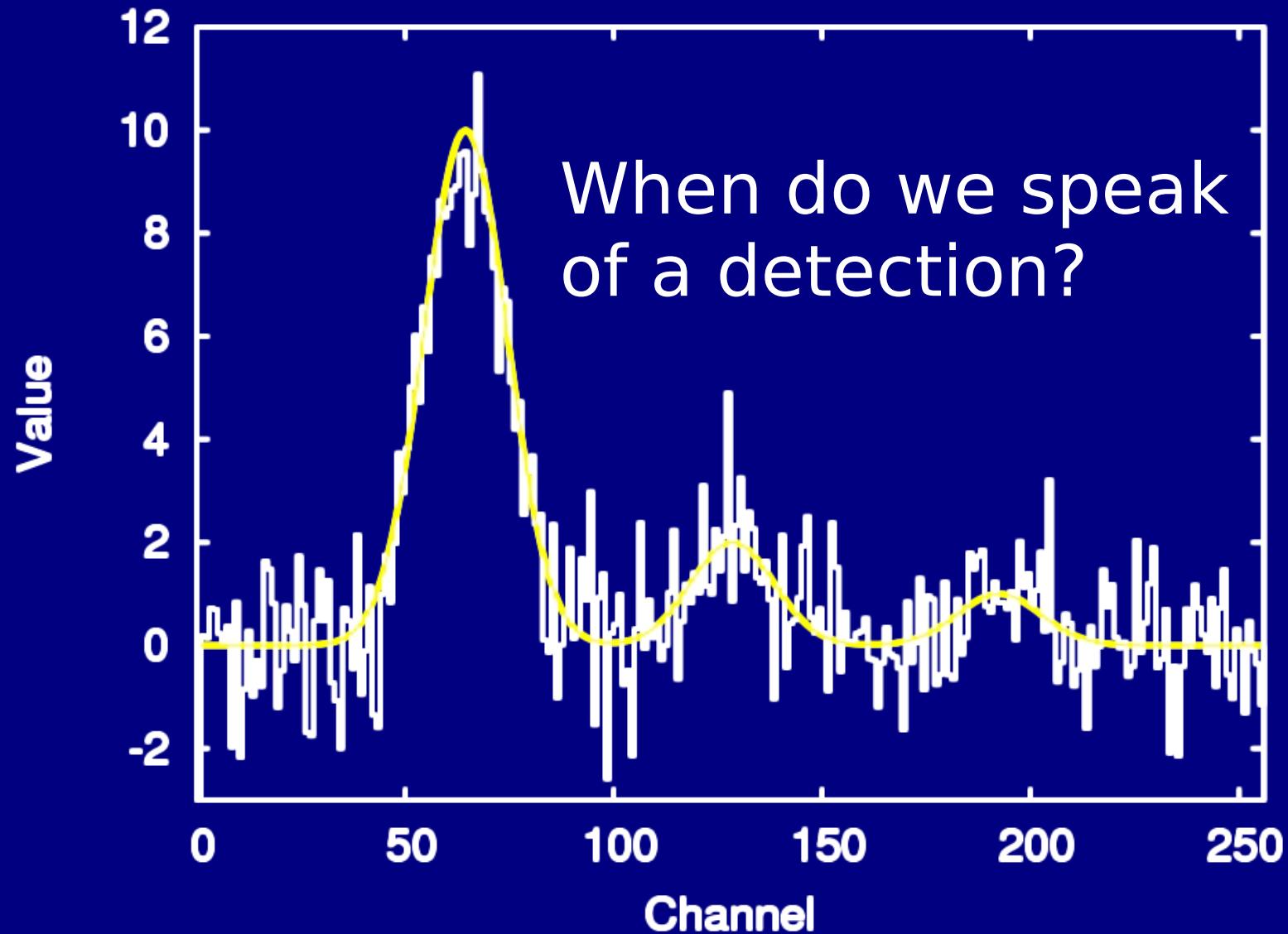
Moments: bottlenecks



Moments and data cubes

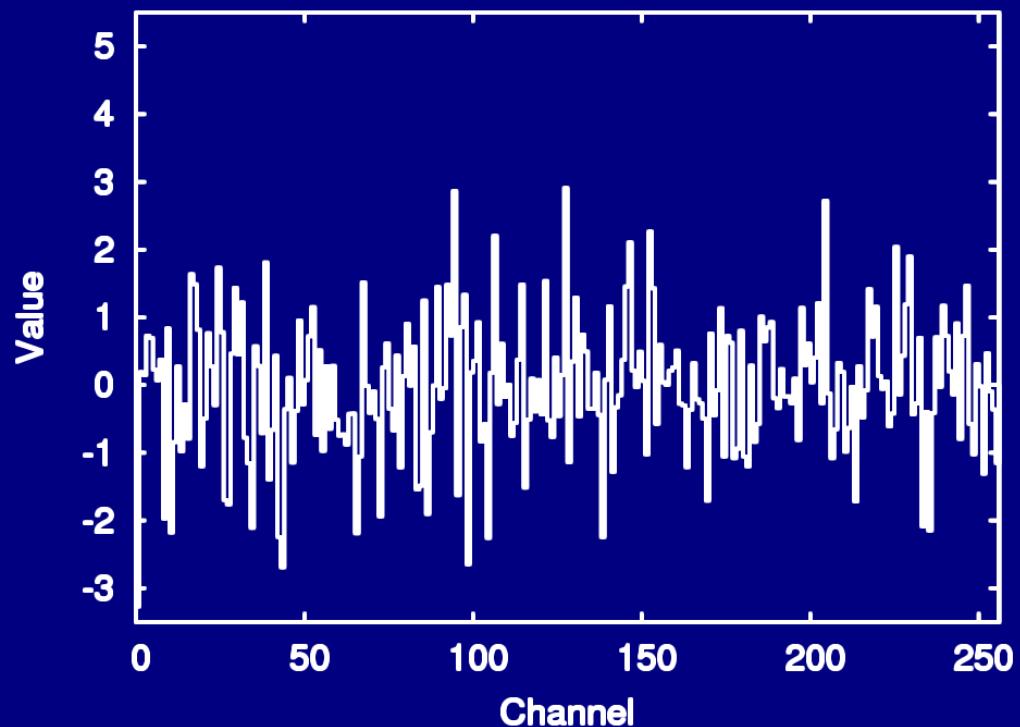
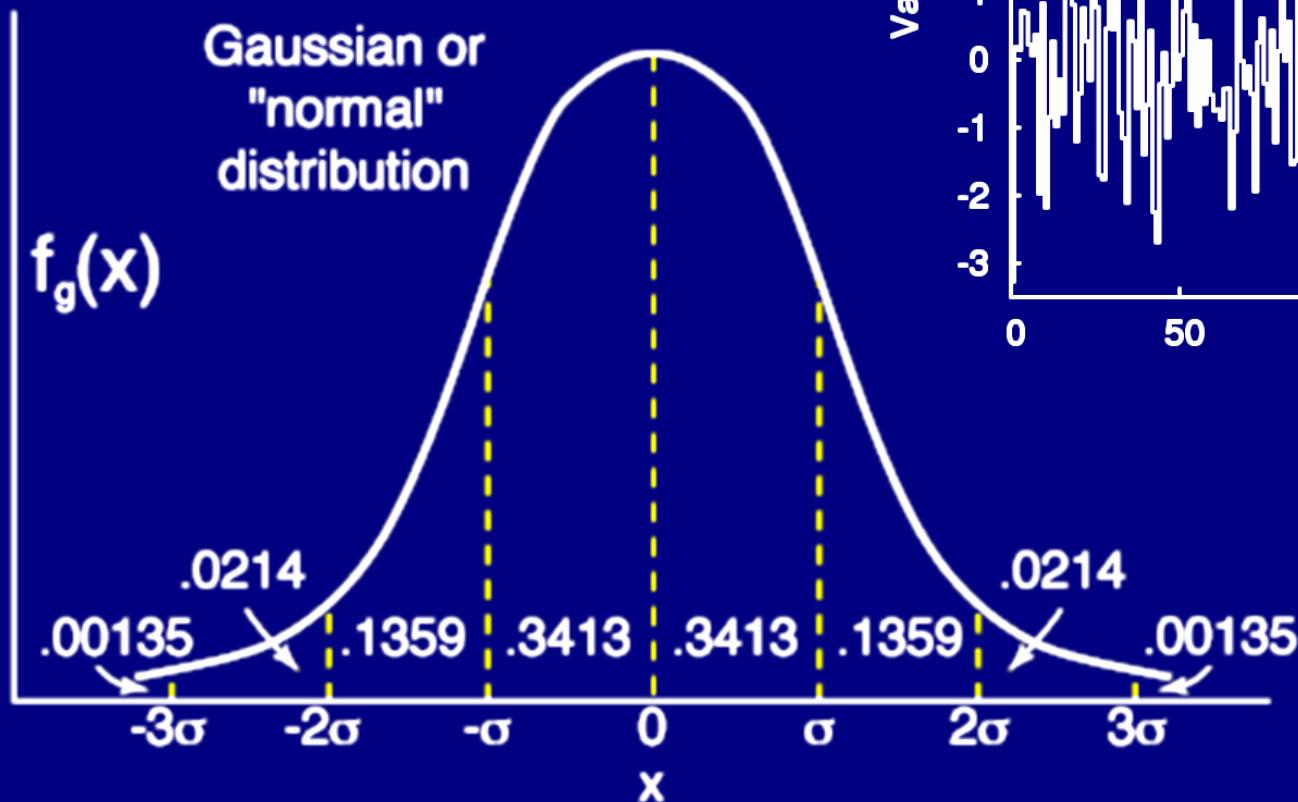


Noise and detections



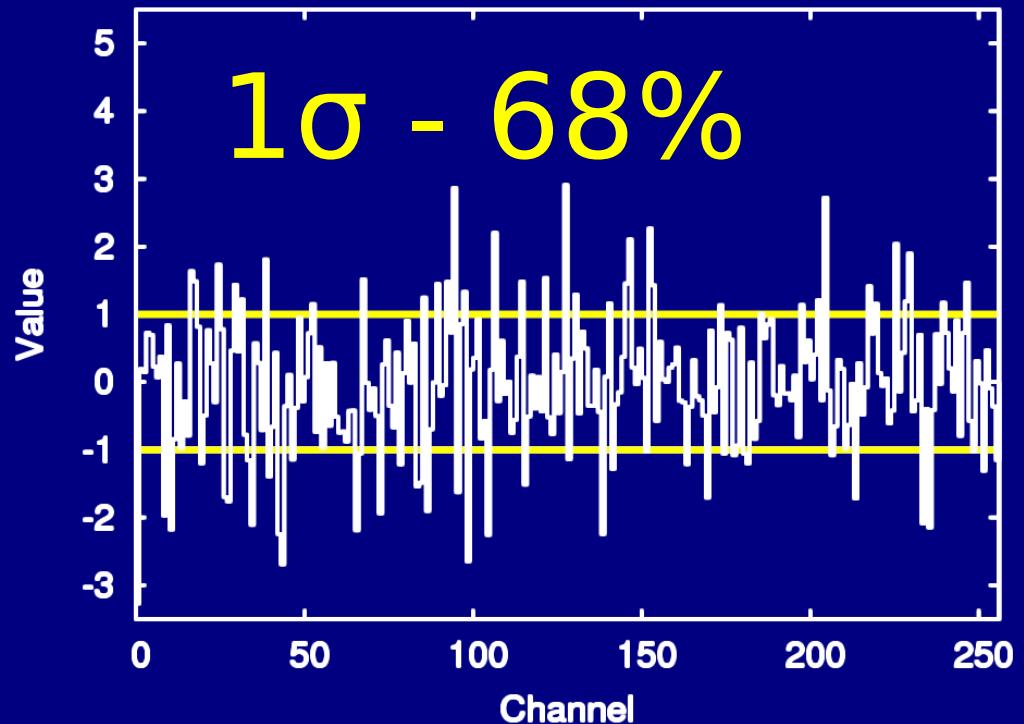
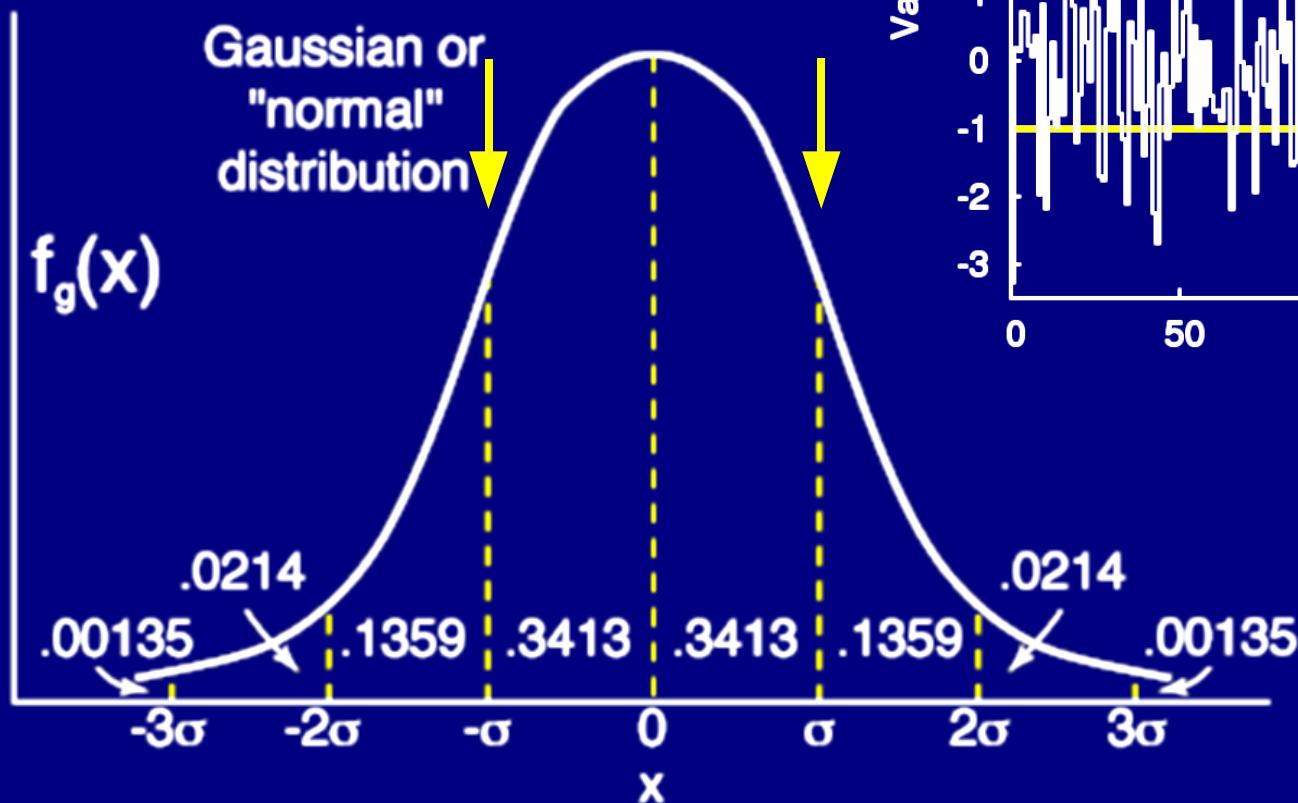
Noise and detections

Noise statistics



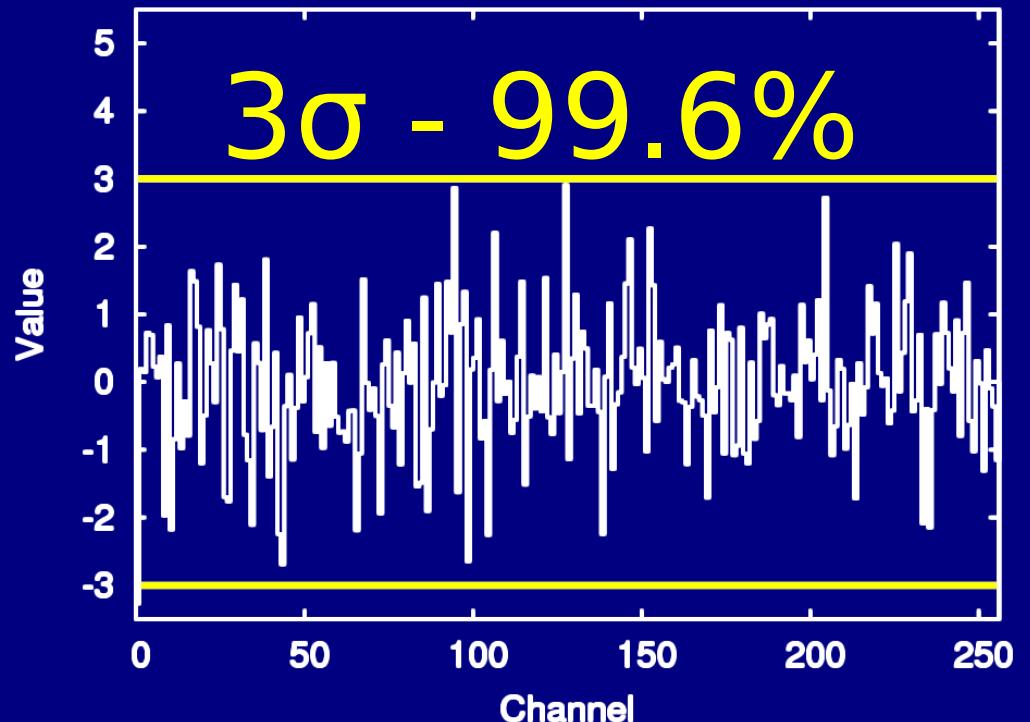
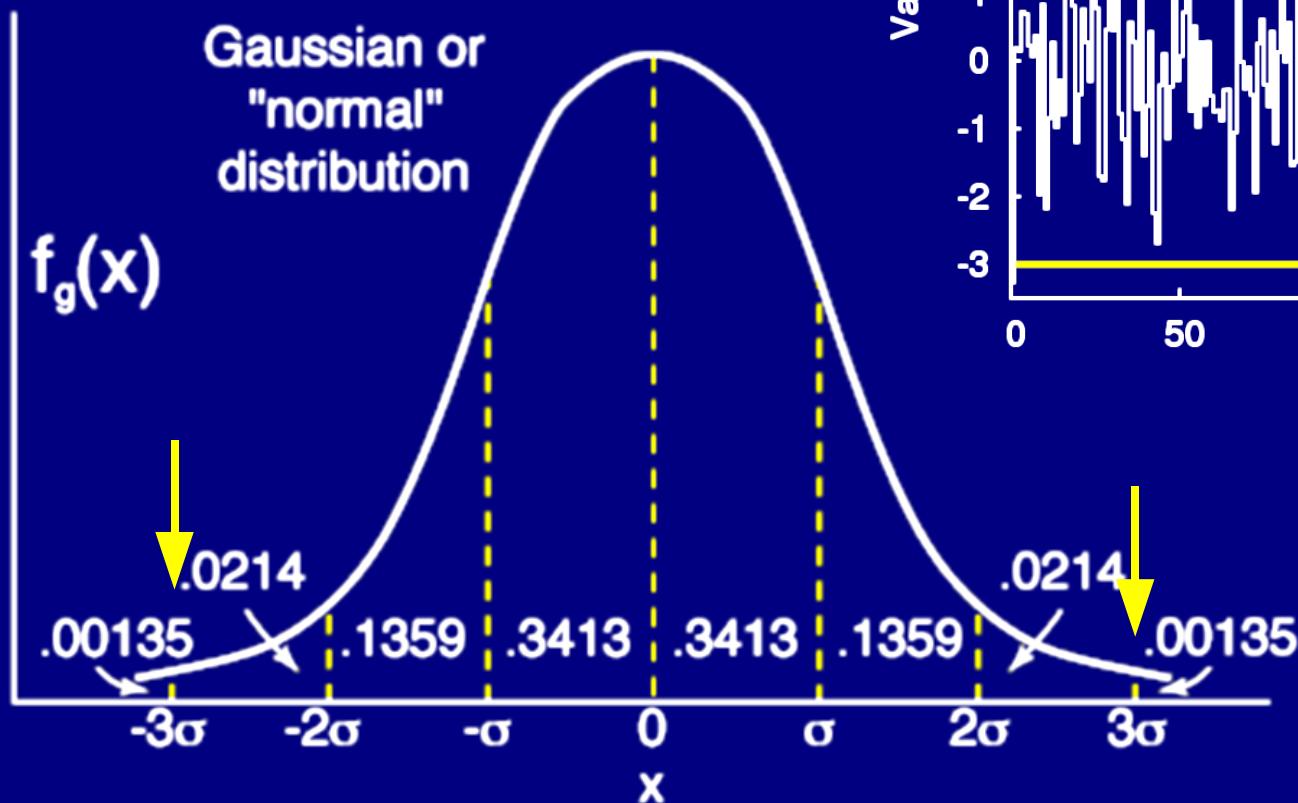
Noise and detections

Noise statistics



Noise and detections

Noise statistics



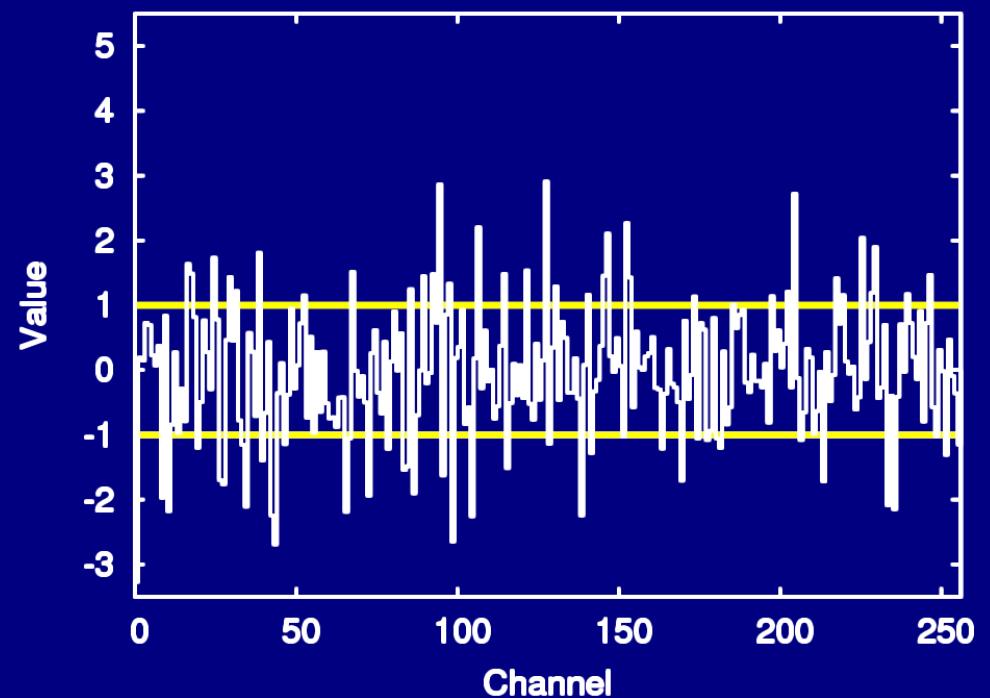
Noise and detections

How to estimate the noise

$$\sigma = \sqrt{\frac{1}{N} \sum_i (x_i - \bar{x})^2}$$

$$\sigma = \sqrt{\frac{1}{N-1} \sum_i (x_i - \bar{x})^2}$$

$$\text{RMS} = \sqrt{\frac{1}{N} \sum_i x_i^2}$$



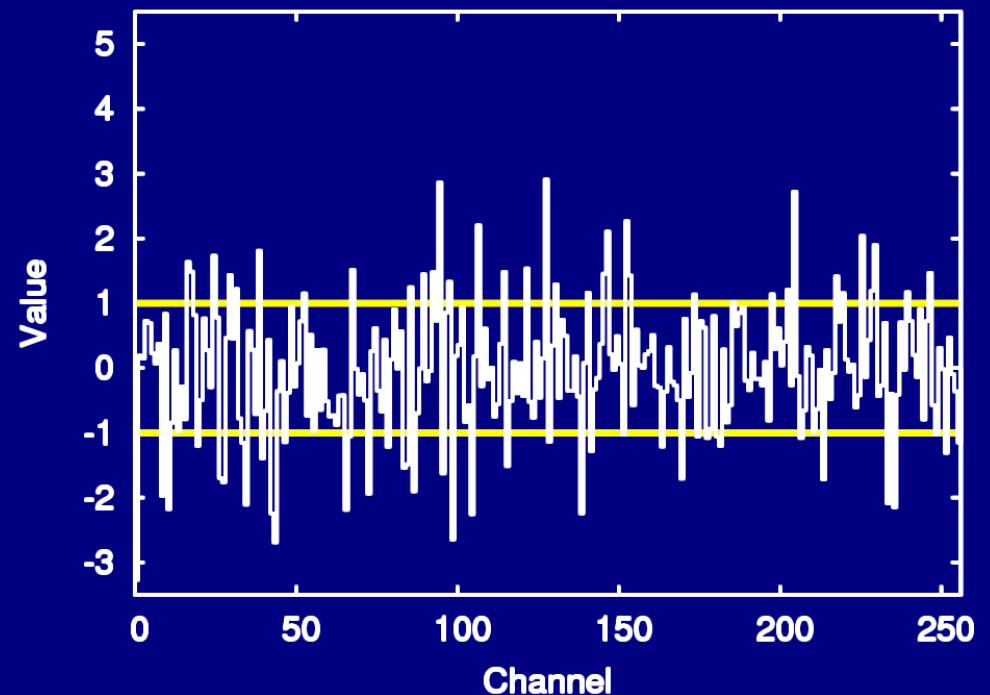
Noise and detections

How to estimate the noise

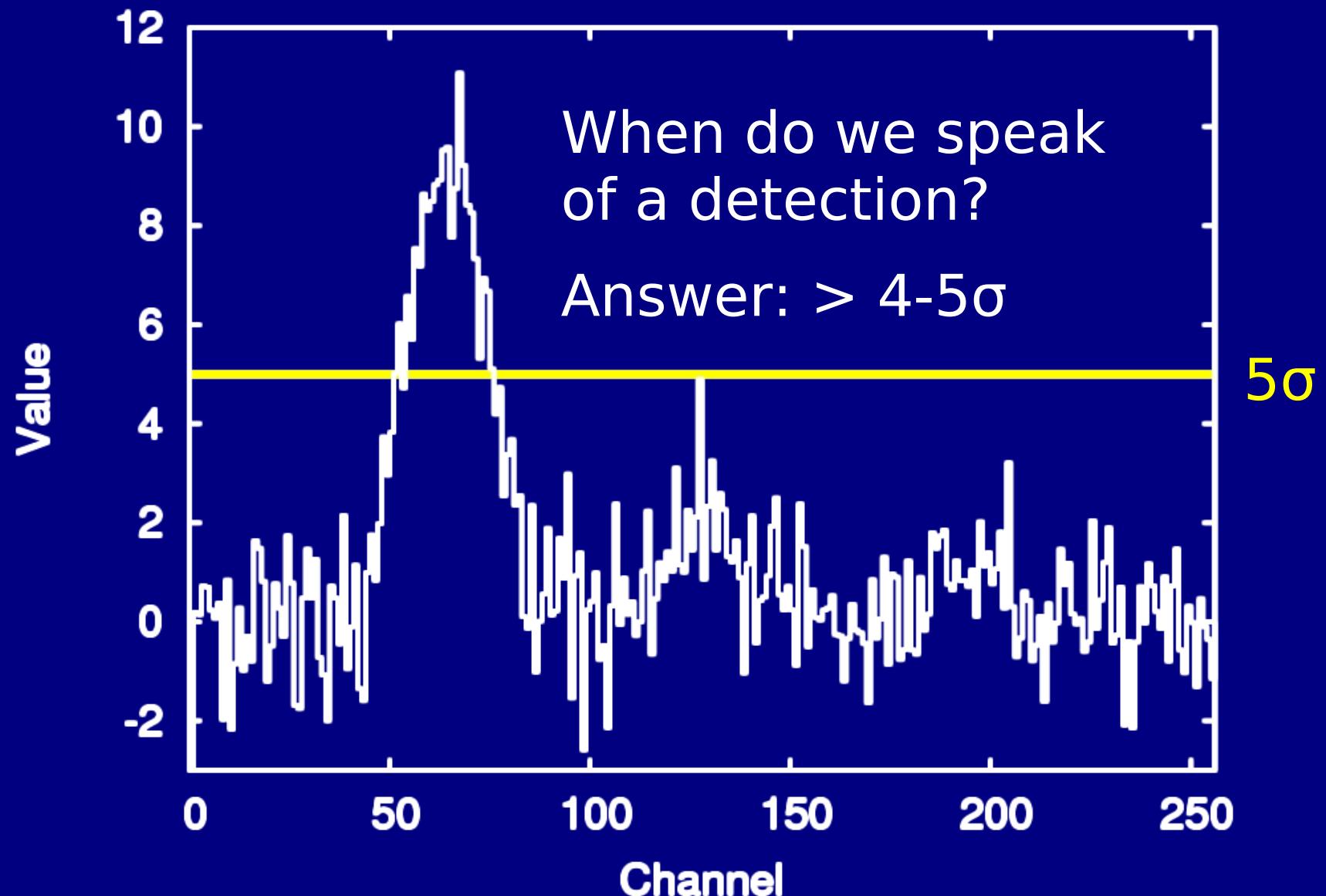
$$\sigma = \sqrt{\frac{1}{N} \sum_i (x_i - \bar{x})^2}$$

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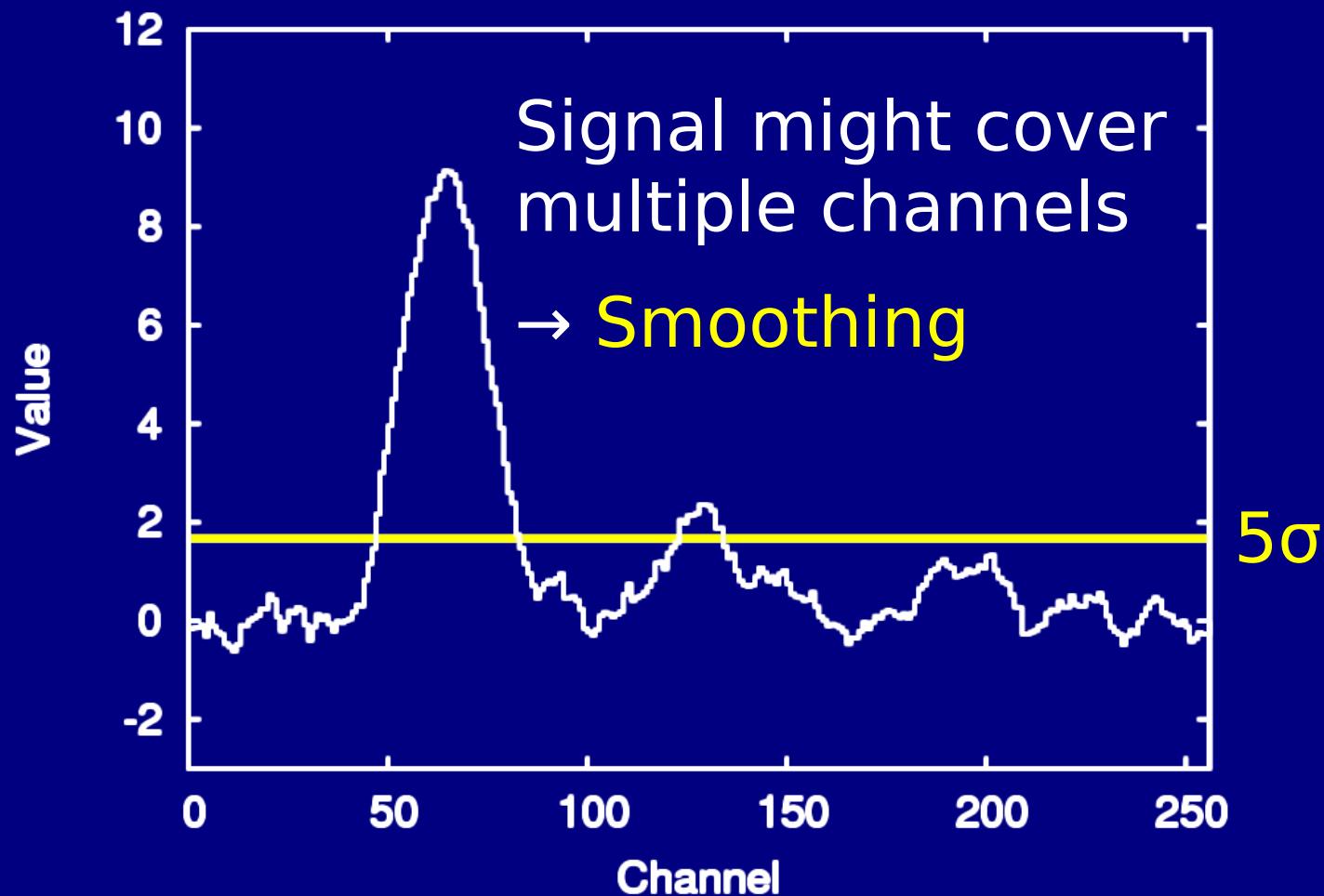
$$\text{RMS} = \sqrt{\frac{1}{N} \sum_i x_i^2}$$



Noise and detections



Noise and detections



Noise goes down with $1/\sqrt{\text{number of averaged spectral channels}}$

Useful formulae

- Can use **Gaussians** to fit emission lines
(also multiple components)

$$g_i(v) = A_i \exp \left[-\frac{(v - v_i)^2}{2\sigma_i^2} \right]$$

Mean velocity

Peak intensity

Velocity width (dispersion)

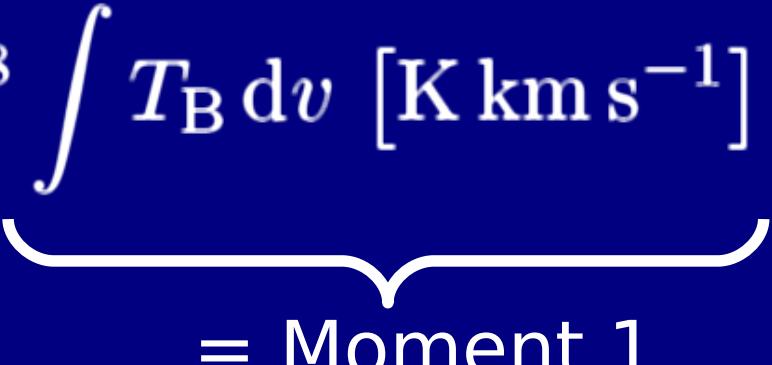
- Often, the **Full-Width Half-Maximum** is used:

$$\Delta v_{\text{fwhm}} = \sqrt{8 \ln 2} \sigma$$

Useful formulae

- Column density

$$N_{\text{HI}}[\text{cm}^{-2}] = 1.823 \cdot 10^{18} \int T_{\text{B}} \, dv [\text{K km s}^{-1}]$$


= Moment 1

→ Column density map follows directly
from the Moment 1 map

- Upper kinetic temperature limit (for HI)

$$T[K] = 21.8 \cdot \Delta v_{\text{fwhm}}[\text{km/s}]^2$$

Useful formulae

- Mass

$$M_{\text{HI}} [\text{M}_\odot] = 7.95 \cdot 10^{-9} (d[\text{Mpc}])^2 \tan^2 \varphi \sum_i N_{\text{HI}}^{(i)} [\text{cm}^{-2}]$$

Distance

Angular size of pixels



Column density in pixel i
(of the column density map)

Problem: distance often unknown

Thank you!