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RESEARCH GROUP
ADVANCED GEODESY
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Session 3

First steps of processing space VLBI data with VieVS

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- Space VLBI = VLBI with sources alternatively to quasars, mostly within the solar system
- e. g. differential VLBI (D-VLBI)
 - Spacecraft navigation (→ Ephemerides)
- Several new & interesting missions
 - NASA (DSN)
 - ESA (Δ DOR)
 - JAXA (Selene, Selene 2)
 - SHAO (Chang'e-1, Chang'e 2, YH Mars orbiter)
 - "VLBI transmitters" on satellites
- Opens up new possibilities for
 - Navigation
 - Frame ties
 - in space
 - between reference frames

1) Specify system configuration

- Signal, frequency
- Single vs. Differential

no

2) Observe & correlate

- Solve ambiguities

no

3) Process

- Delay modelling
- Realized in VieVS

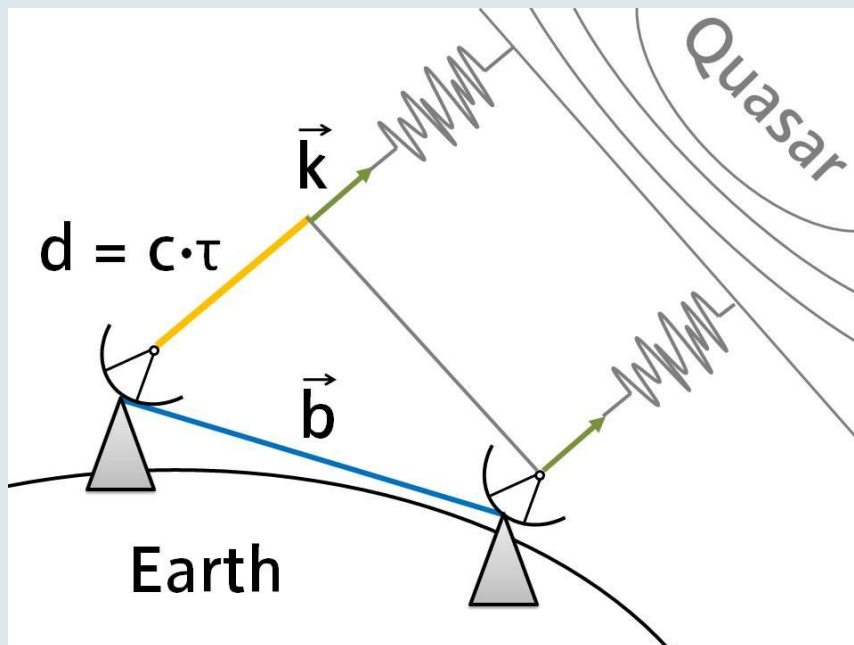
yes



Geodetic vs. Space VLBI

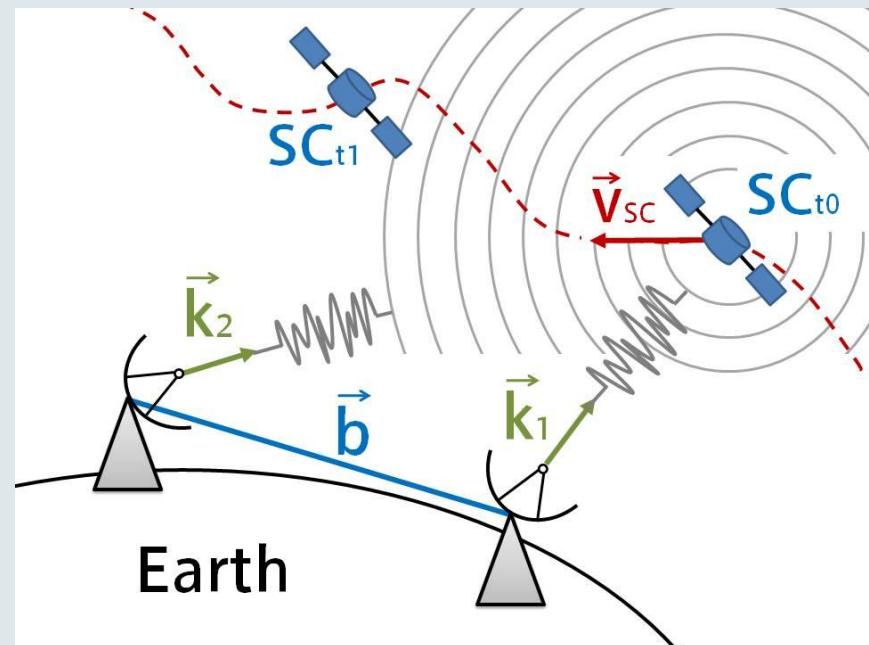
GEODETTIC VLBI

- plane wave front
- stable sources



SPACE VLBI

- curved wave front
- fast moving sources
- time of emission t_0



2 experiments

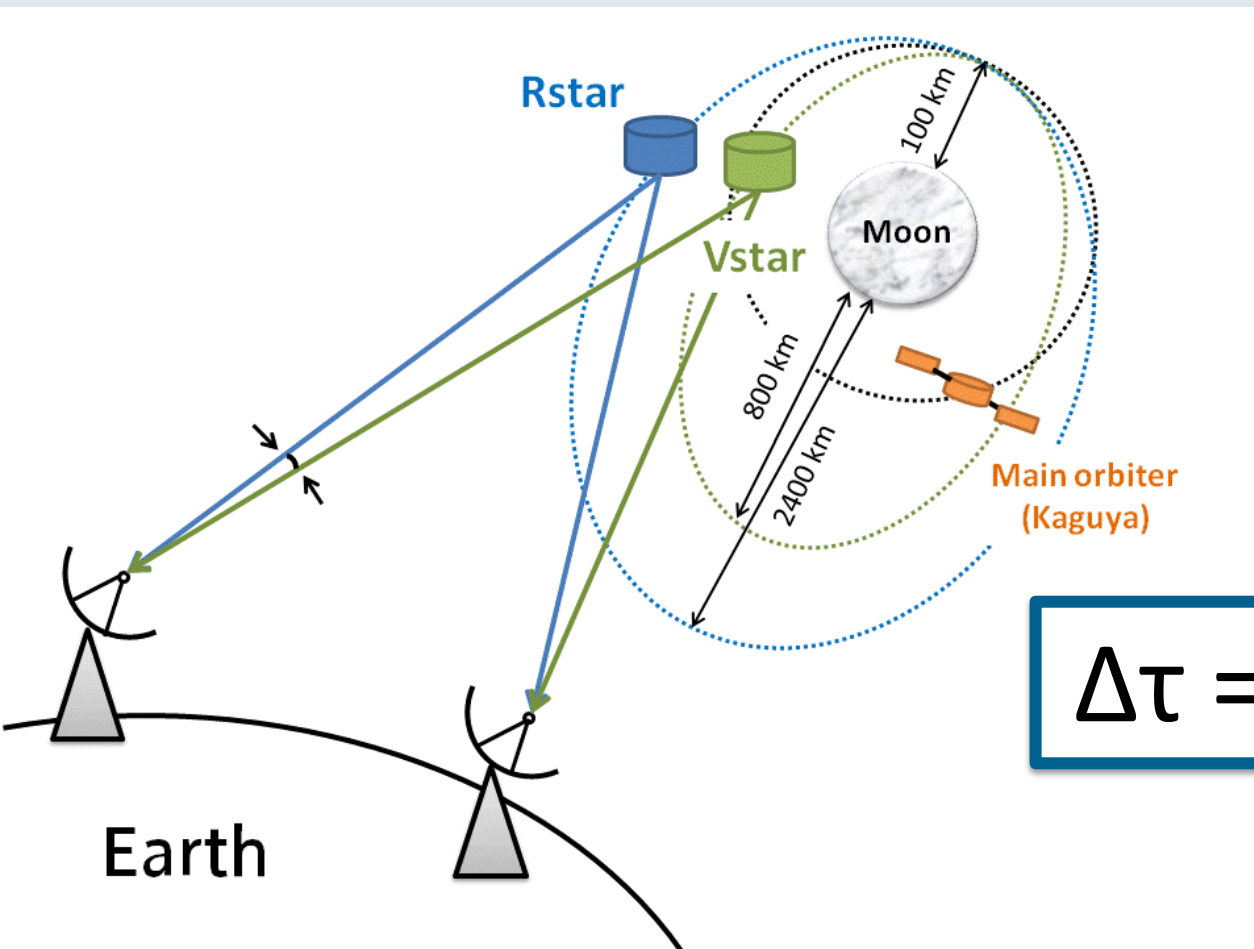
1

Same beam differential
VLBI data from Selene

2

VLBI observations of
GNSS satellites

1: D-VLBI data from Selene



- differential (D-) VLBI data
- same beam

$$\Delta\tau = \tau_{RSTAR} - \tau_{VSTAR}$$

- many effects are the same for τ_{RSTAR} and τ_{VSTAR}

1: D-VLBI delay model

Fukushima & Sekido, 2006:

“A VLBI delay model for radio sources at finite distance”

- Light time iteration

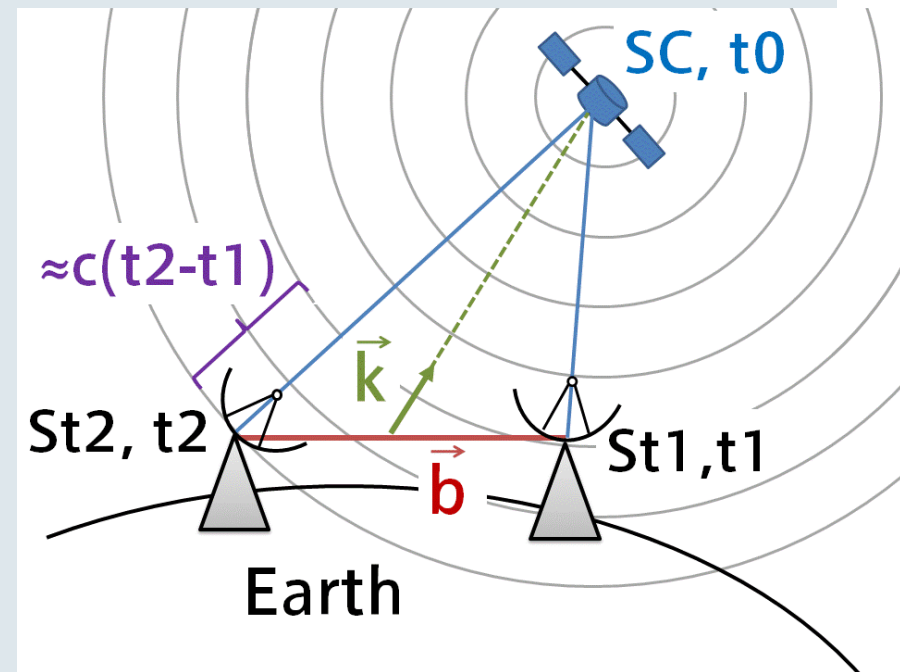
$$t_0(i+1) = t_0(i) - \frac{SC_{t_0} - StI_{t_1}}{c} - \tau_{grav}$$

- Pseudo direction vector

$$\vec{k} = \frac{\vec{R}_1(t_1) + \vec{R}_2(t_1)}{R_1(t_1) + R_2(t_1)}$$

- Correction term

$$\approx \vec{v}_2(t_2 - t_1) / c$$



1: processed Selene data

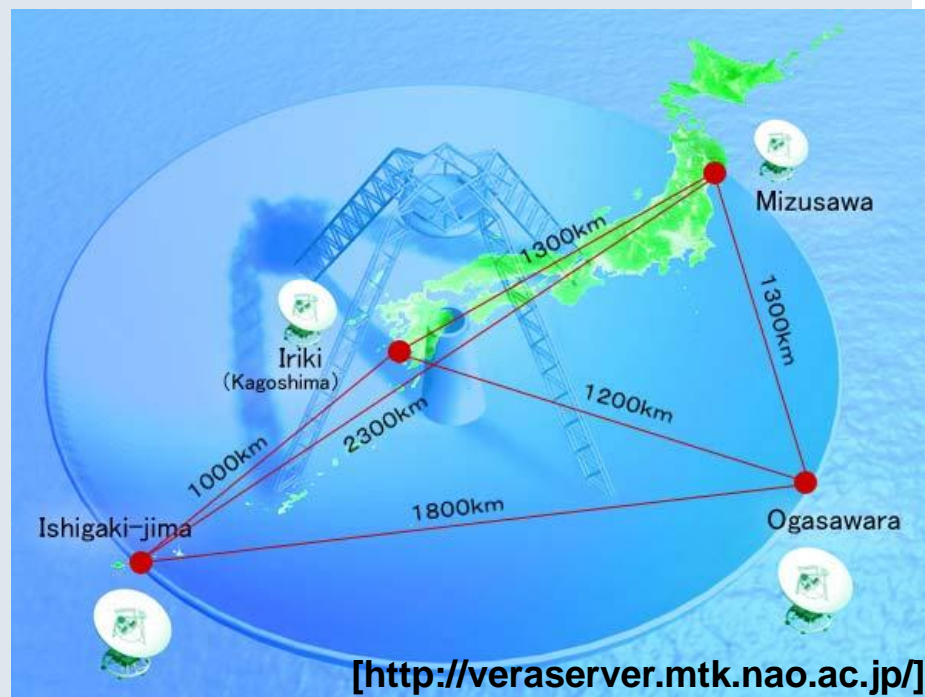
- Selene same beam data is provided by RISE group at NAOJ Mizusawa
- Nominal accuracy (differential phase delay rms), [Kikuchi et al., 2009]:

3.44 ps (1 mm) S-band

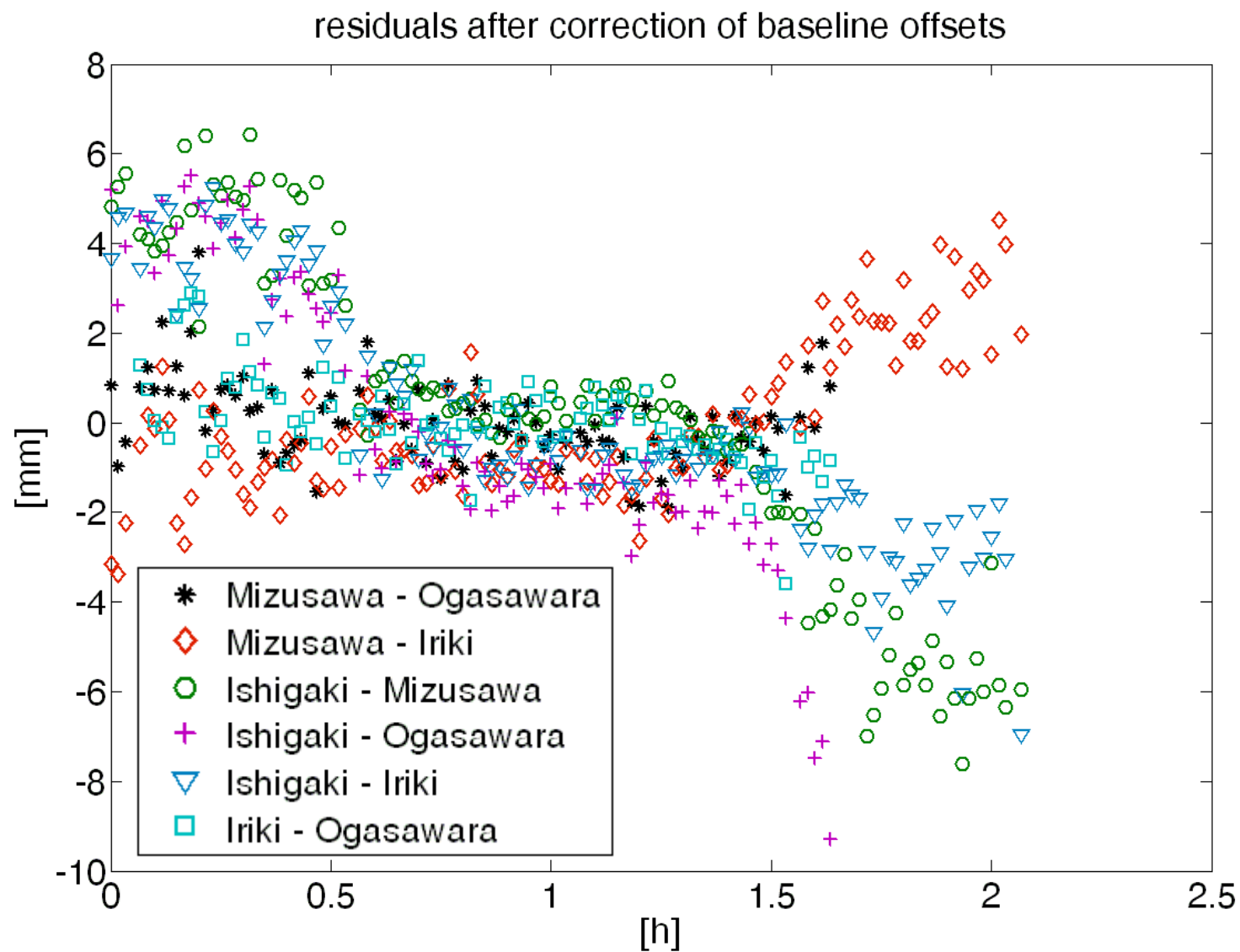
0.64 ps (0.2 mm) X-band

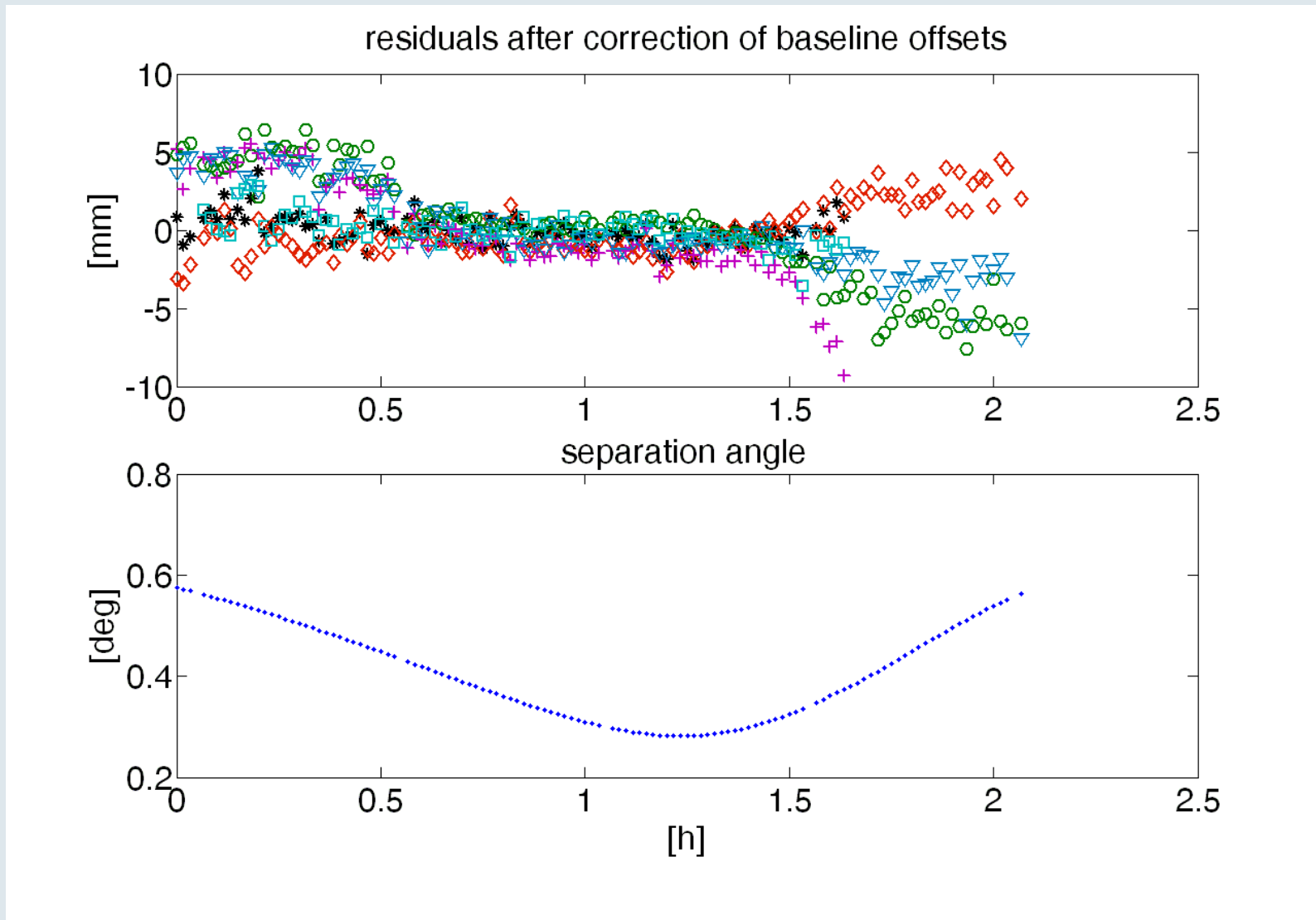
- S-band same beam data from 4 VERA stations of October 19 2008, 17-19 UT

Mizusawa,
 Iriki,
 Ishigaki,
 Ogasawara



- Plotted residuals: $\Delta\tau$ observed-computed (6 baselines),
1 offset per baseline estimated





- Observe GLONASS satellites with VLBI

- Tornatore et al., 2010
- Single source VLBI

- Delay model:

- Klioner, 1991
- Everything is modelled in GCRS

- Simulations performed:

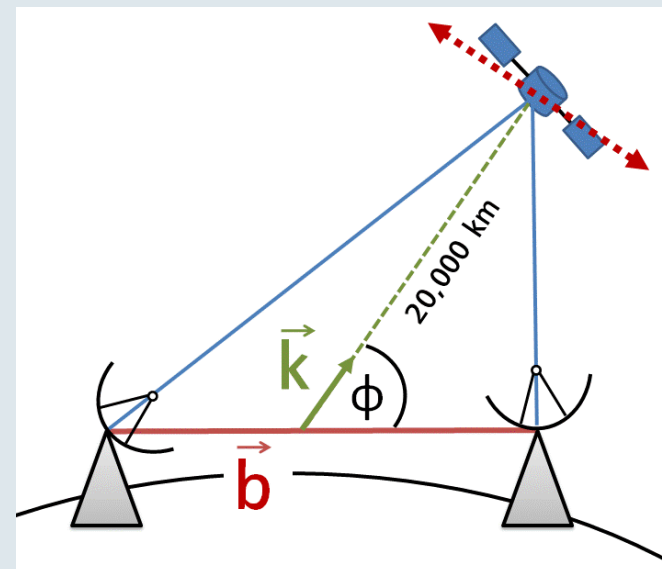
- Vie_sim

- Parameter: $\phi_0 + d\phi$

- Partial: $\frac{d\tau}{d\phi}$

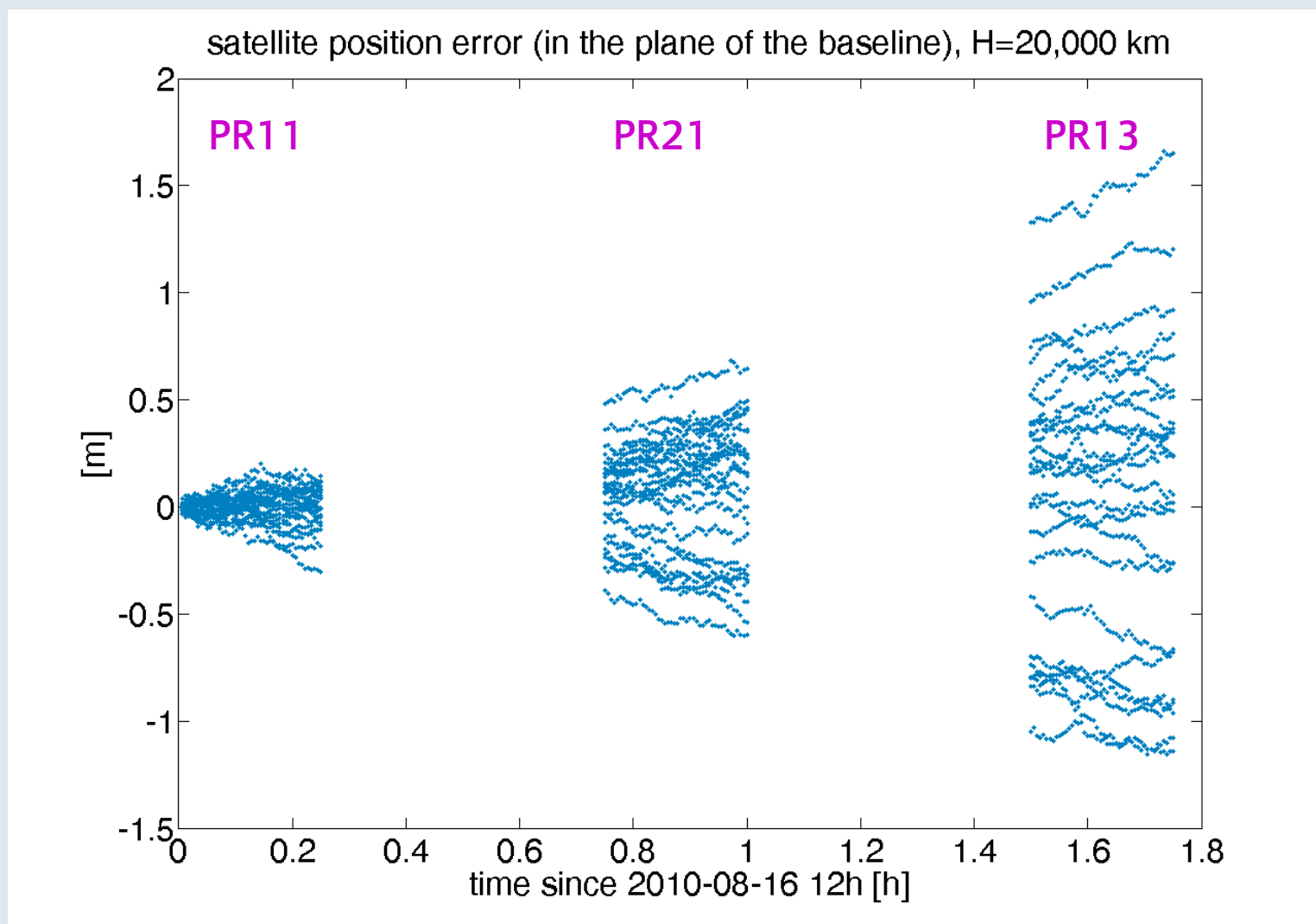
- Experiment:

time:	2010 Aug 16
antennas:	Medicina, Onsala
sources:	GLONASS PR11, PR13, PR21
observations:	12:00 – 13:45, 20" interval



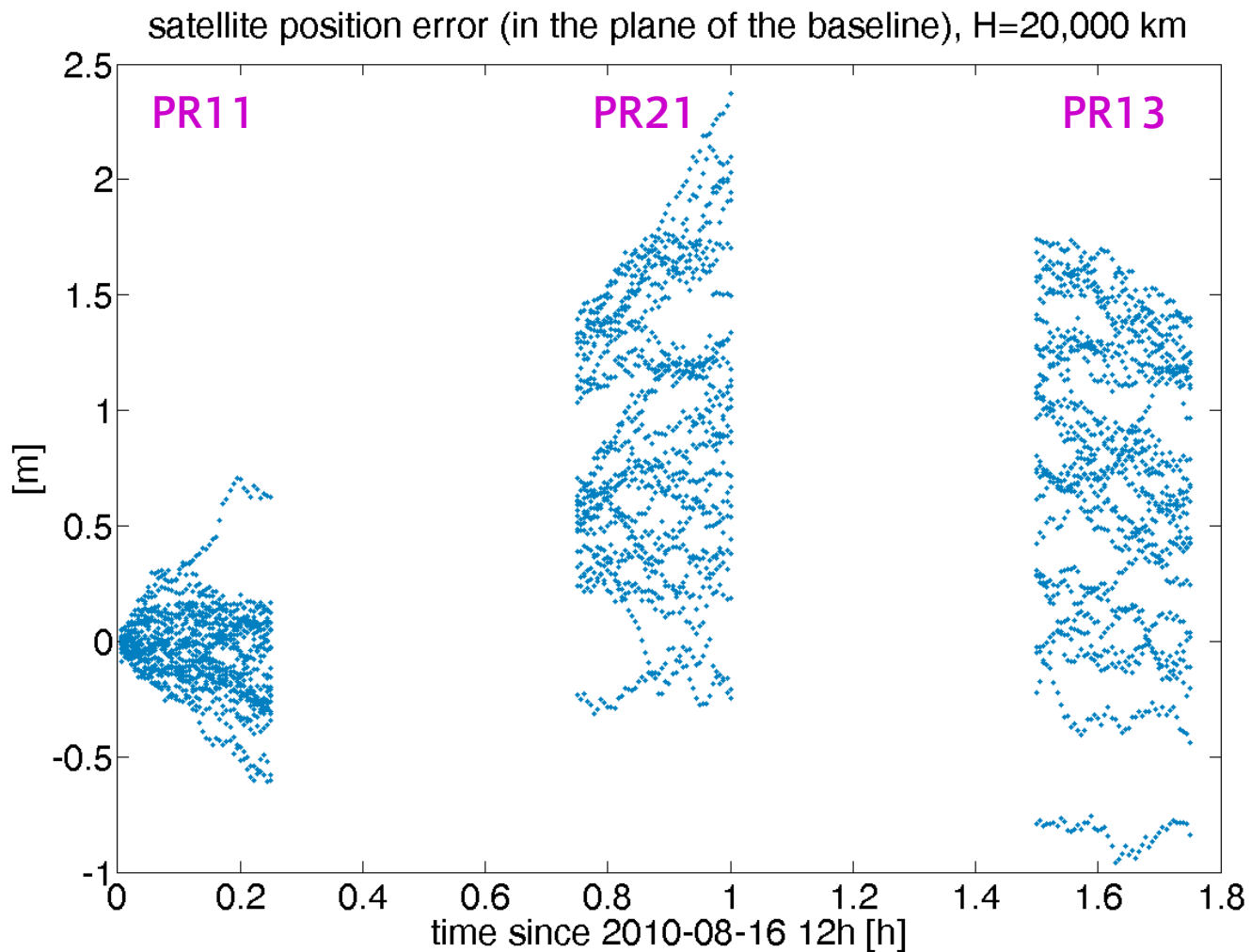
2: GNSSVLBI - simulation

Clock drift $1e-14$ @ 50 min, 25 days simulated



Simulated slant wet delay

$C_n = 2.5^{-7} \text{ 1/m}^3$
 $H = 2000 \text{ m}$
 $wzd_0 = 150 \text{ mm}$
 $v_n = 0 \text{ m/s}$
 $v_e = 8 \text{ m/s}$



- We successfully used VieVS to model delays of space VLBI applications; we implemented
 - Selene same beam data processing and
 - Glonass GNSS observations
- A simple estimation tool (`vie_lsm_sc`, `vie_lsm_gnss`) exists and can be used for simulations

TO DO:

- Improve model
 - External ionosphere / troposphere corrections
- Improve estimation part
 - Choose parameters
 - Constraints for trajectory of the space craft
- Continue work with real data

THE END

Thank You for listening!

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References:

- Kikuchi et al., 2009: *Pico-second accuracy VLBI of the two sub-satellites of SELENE (KAGUYA) using multi-frequency and same-beam methods*, Radio Sci. 44(RS2008).
- Klioner, 1991: *General relativistic model of VLBI observables*. In: Carter WE (eds) Proceedings of AGU Chapman conference on geodetic VLBI: monitoring of global change. NOAA Technical Report NOS 137 NGS 49, AGU, Washington DC, pp 188-202.
- Sekido & Fukushima, 2006: *A VLBI delay model for radio sources at a finite distance*, J. Of Geodesy, 80:137-149, DOI 10.1007/s00190-006-0035-y.
- Tornatore et al., 2010: *Planning of an Experiment for VLBI Tracking of GNSS Satellites*, D. Behrend and K. D. Baver (eds), IVS2010 GM Proceedings, VLBI2010: From Vision to Reality.