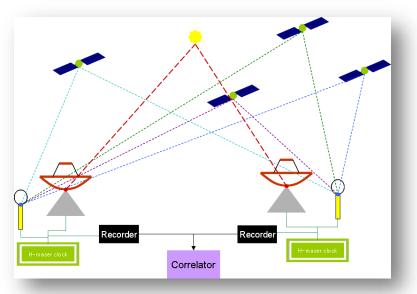
VALIDATION EXPERIMENT OF THE GPS-VLBI HYBRID SYSTEM



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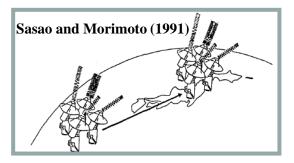




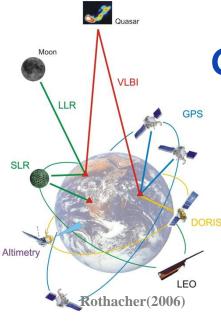


Motivation

Multiple Antennas or Beams







Combination of Space Geodetic techniques







Parameters determined by space geodetic techniques

Techniques	ICRF	EOP					Center of
		Nutation	Polar motion	UT1	LOD	ITRF	Earth mass
VLBI	0	0	0	0	0	0	
GNSS			0		0	0	0
SLR			0		0	0	0
DORIS			0		0	0	0

- **ITRF : International Terrestrial Reference Frame**
- **ICRF : International Celestial Reference Frame**
- **EOP : Earth Orientation Parameters**







How can we combine space geodetic techniques effectively?

Approach in terms of observation level combination







Ideal partner of VLBI

- Radio wave for co-observation with VLBI
- Many sources and various direction (multi-beam) at one time
- Cheaper than others and easier to install (commercial product)

Global Positioning System

Combination of VLBI and GPS







Enabling technology

that made GPS-VLBI Hybrid system realizable

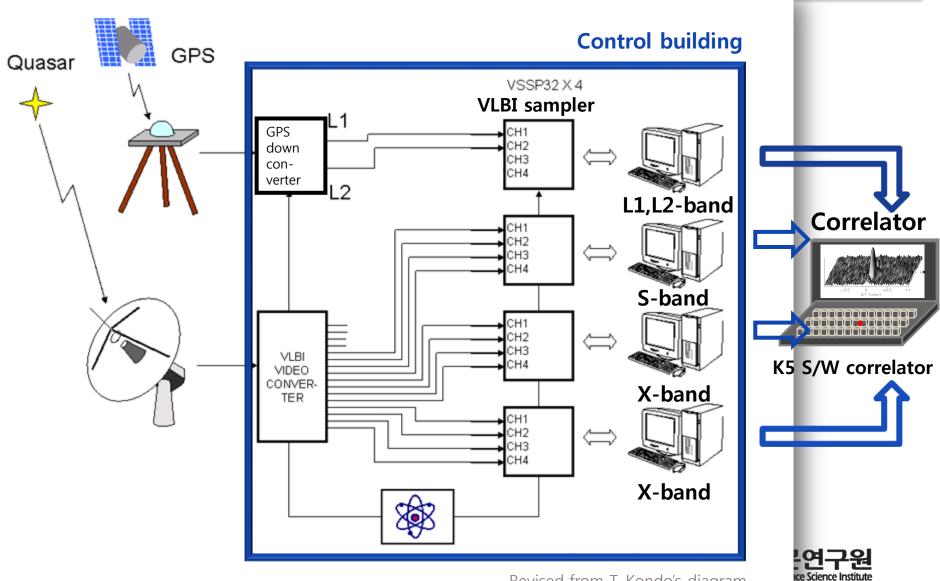
- Development of Digital Processing technique
 - High speed VLBI Sampler e.g. VSSP32
 - Large data volume of recording system
 - S/W correlator with high performance processor e.g. K5 correlator







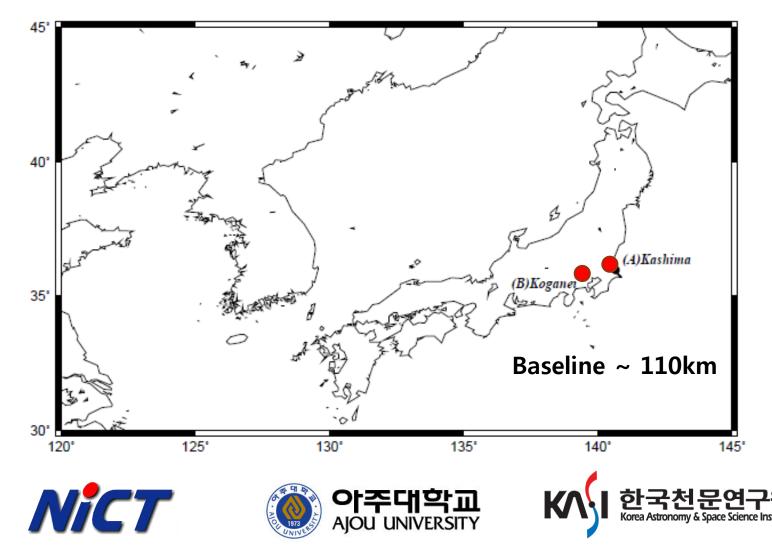
GPS-VLBI hybrid system



Revised from T. Kondo's diagram

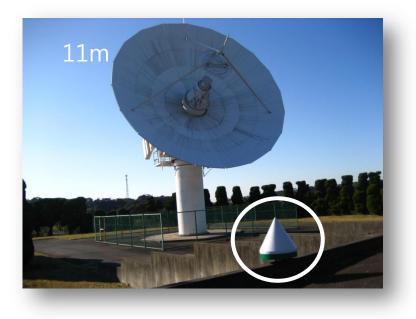
24-hour GV Hybrid Observation





Antennas for the 24-hour experiment with GV Hybrid System

Kashima



Koganei









GPS-VLBI Hybrid Observation

VLBI
Normal VLBI 24hr session

• GPS

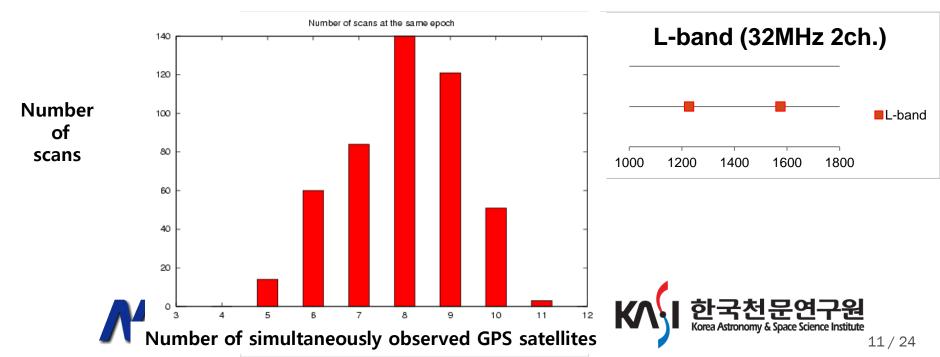
To reduce GPS data volume to 1/3 1min. on + 2 min. off GPS 24hr session





Correlation Processing

Freq. band	S X		L1	L2
# of channels	4	4 8		1
Bandwidth synthesis	0	0	X	x
Integration time	Scan duration	Scan duration	60s	60s
# of targets	-	-	F 11	F 11
at one scan	L	L	5~11	5~11





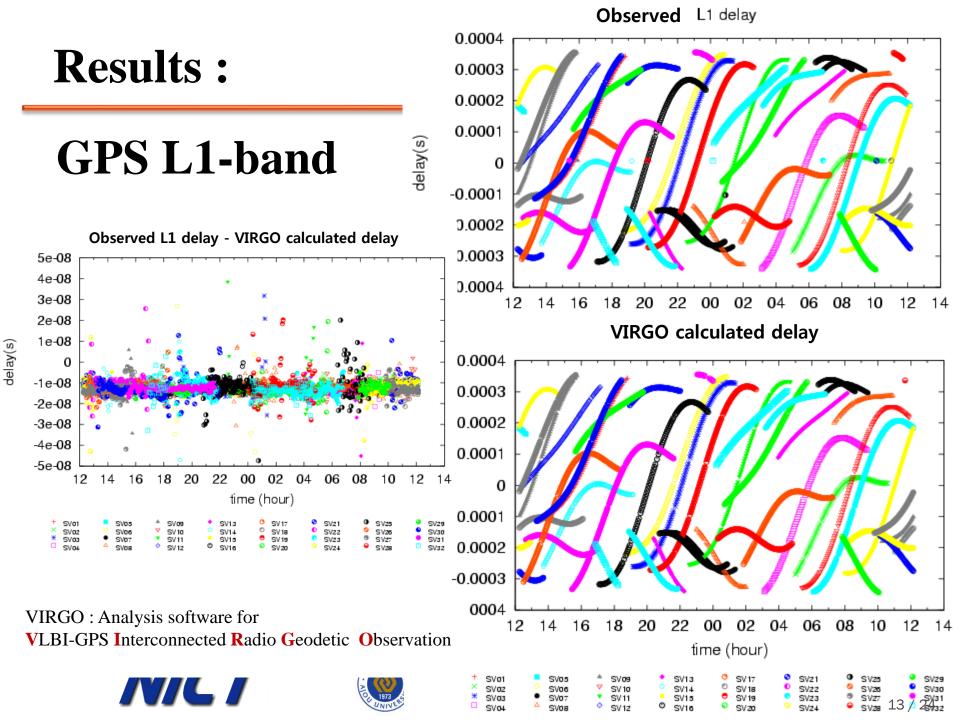
GPS Group delay

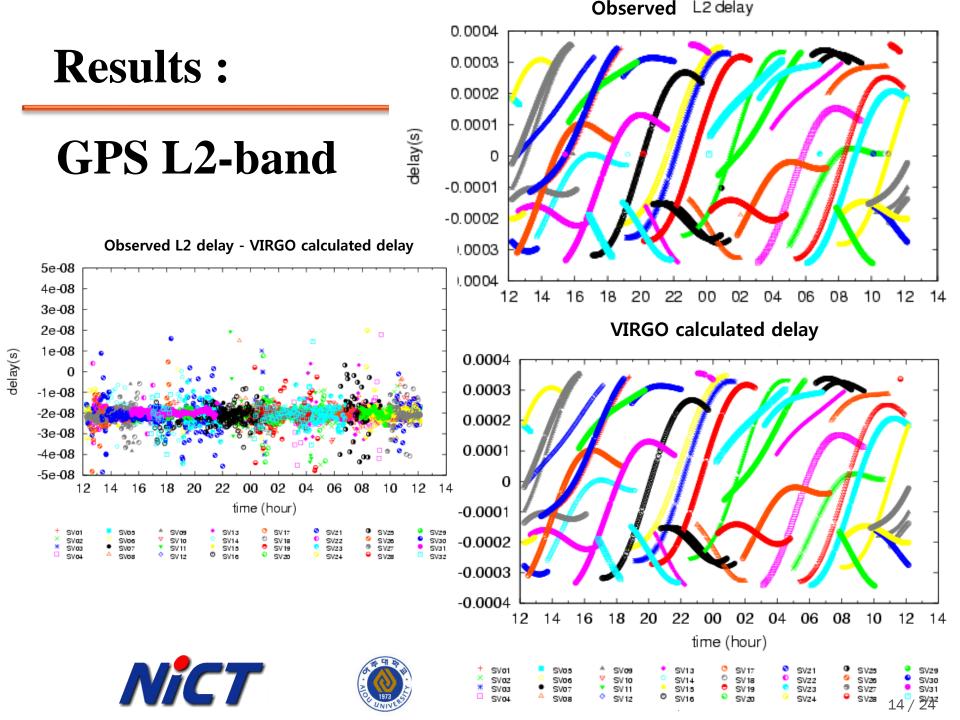






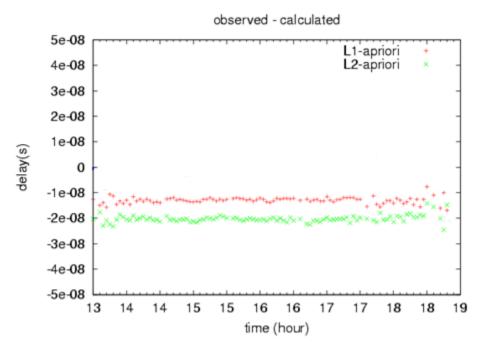
12/24





Results : Difference in L1 and L2 cables

e.g. SV01



✓ Difference in L1 and L2 cables







Cables for the experiment with GV Hybrid System

No phase/cable calibrator for GPSGPS cables on the air





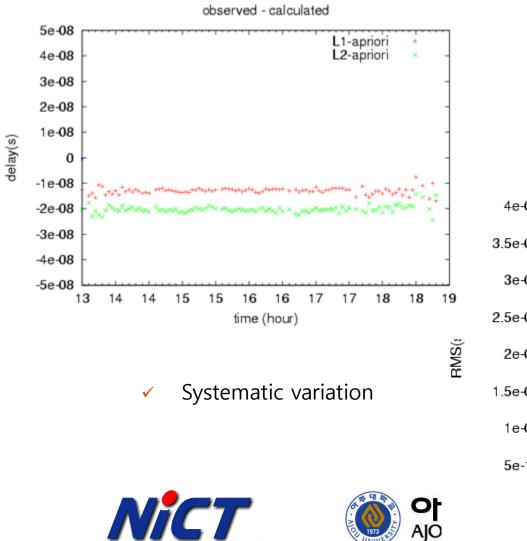


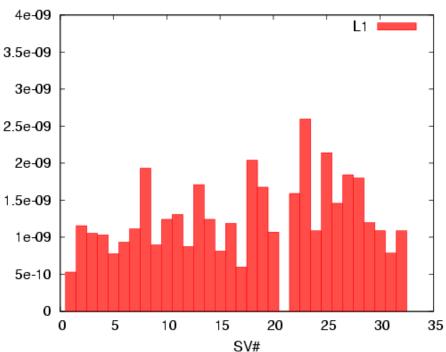




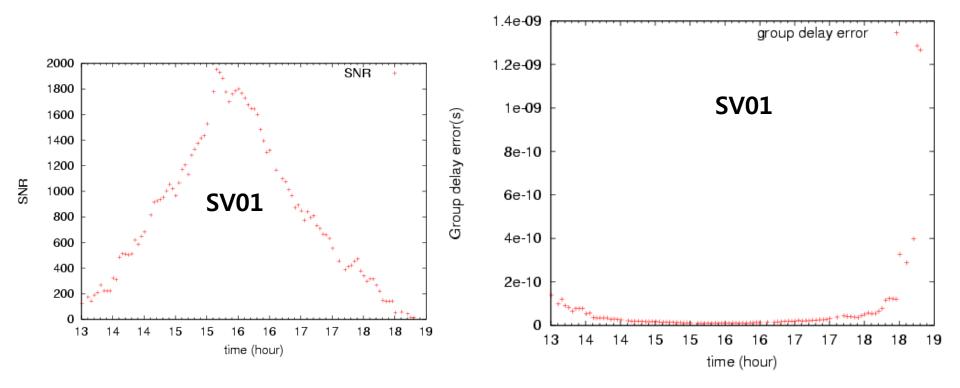
Results : Low cut filtered L1 O-C







SNR & white noise assumed Group delay error (SV01)



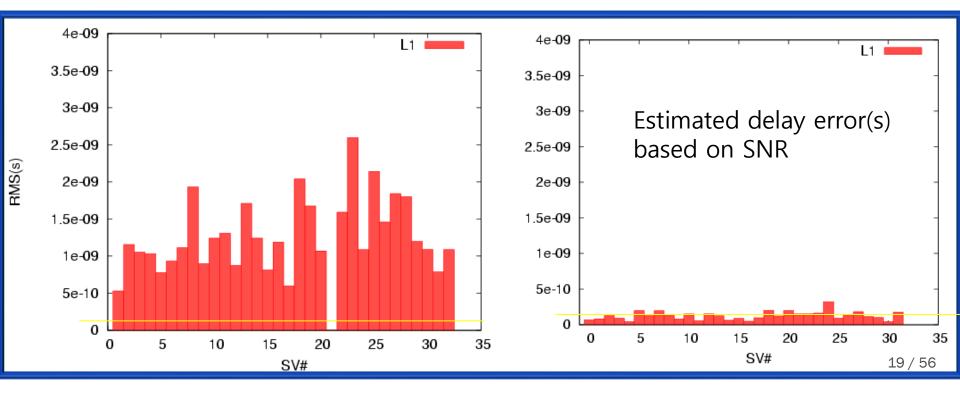






Results : L1

Low cut filtered L1 O-C VS White noise assumed Group delay error(SV01)



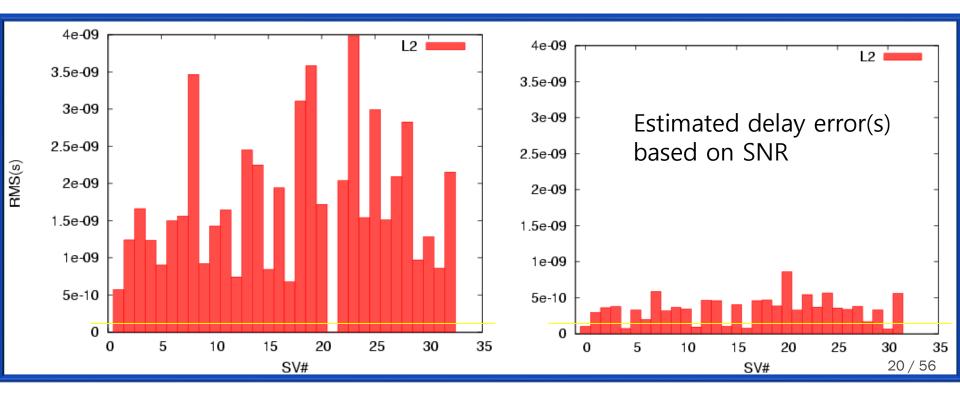






Results : L2

Low cut filtered L1 O-C VS White noise assumed Group delay error(SV01)









Possible Causes of Large Scatters in GPS O-C

Known Things

• A prioris

- We used IGS broadcast ephemeris in calculating geometric delay
- Wet delay not included
- Measurements
 - No phase/cable calibrator

Other Things can be considered

- Spectral characteristic of GPS signal was not considered in correlation model
- Phase center problems were not took into account







Conclusion

- GPS-VLBI hybrid system was successfully developed and GPS signals were reliably sampled, recorded, and correlated in VLBI system during 24-hour experiment
- Many GPS satellites showed high SNR which would yield 0.1 nsec level of thermal noise error assuming white noise.
- However, actual O-C of GPS group delays show nanosecond level scatter







Conclusion

We need further investigation in

- better delay model (use of precise ephemeris)
- better correlation model (proper account of characteristics of GPS signals such as real spectrum, code nature)
- consideration of GPS specific problems such as multipath and phase center
- ✓ better instrumentation (use of phase and delay calibrator, cable duct).







Future Works

- Baseline analysis
- New down converter unit
- New L5 band added
- Lager network in global scale







Thank you for your attention!!!





